

5. SLE(K)

Fix a probability space (Ω, \mathcal{F}, P) on which is defined a Brownian motion $(B_t)_{t \geq 0}$.

Fix $K \in [0, \infty)$ and set $\tilde{z}_t = \sqrt{K} B_t$.

Then $(\tilde{z}_t)_{t \geq 0}$ is Brownian motion of diffusivity K.

Construct from $(\tilde{z}_t)_{t \geq 0}$, as in §4,

$$\dot{g}_t(z) = \frac{2}{g_t(z) - \tilde{z}_t}, \quad g_0(z) = 0$$

$g_t : H_t \rightarrow \mathbb{H}$ conformal isomorphism

$$K_t = \mathbb{H} \setminus H_t.$$

Say that a continuous function $\gamma: [0, \infty) \rightarrow \bar{\mathbb{H}}$
generates $(K_t)_{t \geq 0}$ if

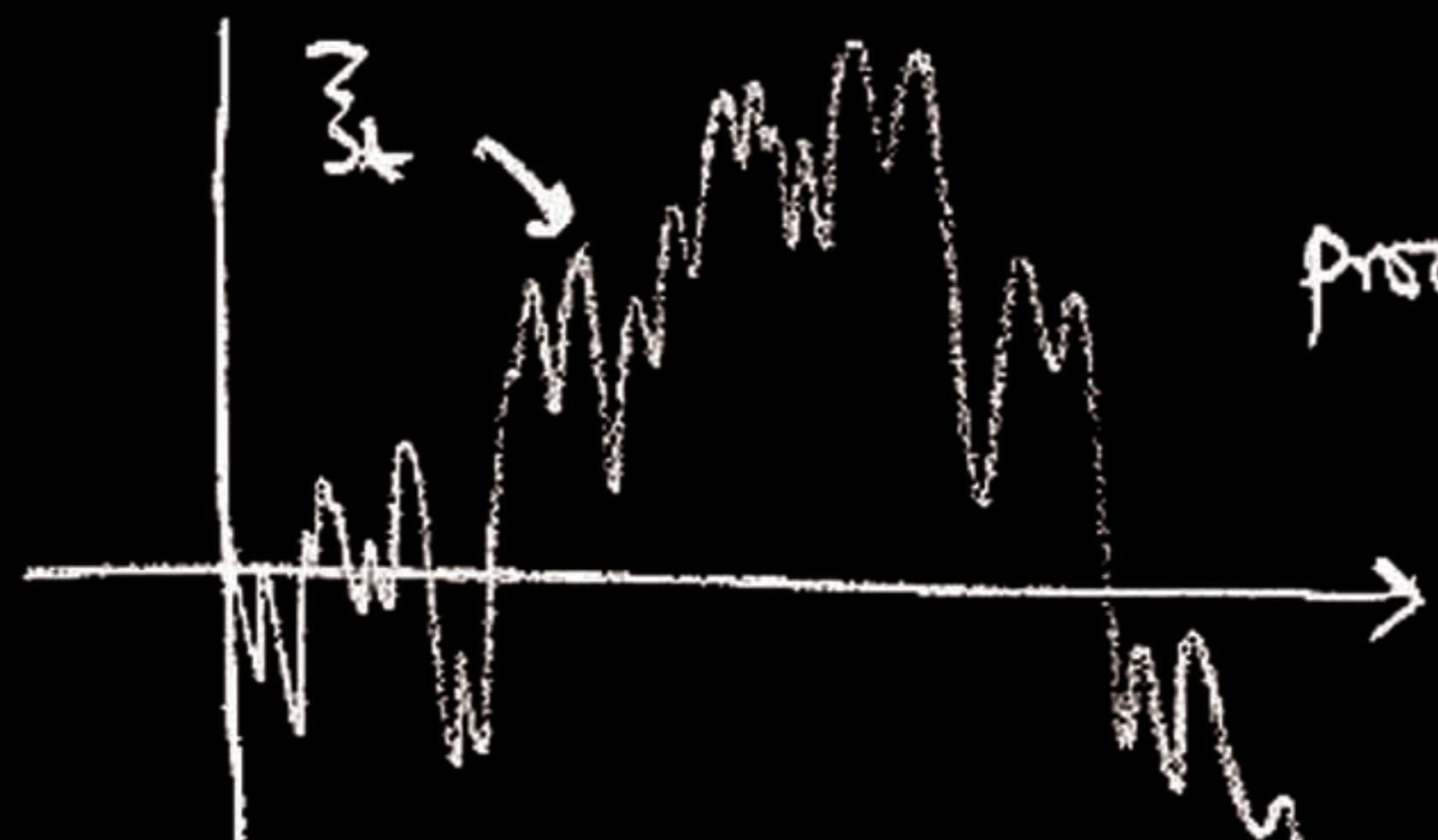
H_t is the connected component of $\mathbb{H} \setminus \gamma[0, t]$ containing ∞ .
Any $(K_t)_{t \geq 0}$ so obtained is a family of compact \mathbb{H} -hulls
having the local growth property.



Theorem 5.1

For all $K \in [0, \infty)$, taking $\beta_t = \sqrt{K} B_t$, there is a unique
continuous random process $(\gamma_t)_{t \geq 0}$ in $\bar{\mathbb{H}}$ generating $(K_t)_{t \geq 0}$.

The process $(X_t)_{t \geq 0}$ is called a stochastic Loewner
evolution of parameter K , or SLE(K) for short.



produces



SLE inherits from Brownian motion a scaling property and a Markov property. Define for $r > 0$ and $s \geq 0$

$$(\epsilon_r \bar{z})_t = r^{-1} \bar{z}_{rt}, \quad (\epsilon_r \gamma)_t = r^{-1} \gamma_{r^2 t}$$

and

$$(\Theta_s \bar{z})_t = \bar{z}_{t+s} - \bar{z}_s, \quad (\Theta_s \gamma)_t = g_s(\gamma_{s+t}) - \bar{z}_s.$$

Then $\epsilon_r \gamma$ and $\Theta_s \gamma$ have Loewner transforms $\epsilon_r \bar{z}$ and $\Theta_s \bar{z}$ respectively.

We know that the distributions of $\epsilon_r \bar{z}$ and $\Theta_s \bar{z}$ do not depend on r and s , with $\Theta_s \bar{z}$ independent of $(\bar{z}_u : u \leq s)$. Hence analogous statements hold for $\epsilon_r \gamma$ and $\Theta_s \bar{z}$.

6. Phases of SLE

The behaviour of $SLE(k)$ changes dramatically as the parameter k is varied. This may initially seem surprising, as scaling a Brownian motion is a simple transformation producing no new effects.

Lemma 6.1

Fix $\alpha \in (0, \infty)$ and consider, for each $x \in (0, \infty)$, the unique maximal solution $(X_t(x))_{t \in \mathbb{S}^{\omega}}$ in $(0, \infty)$ to

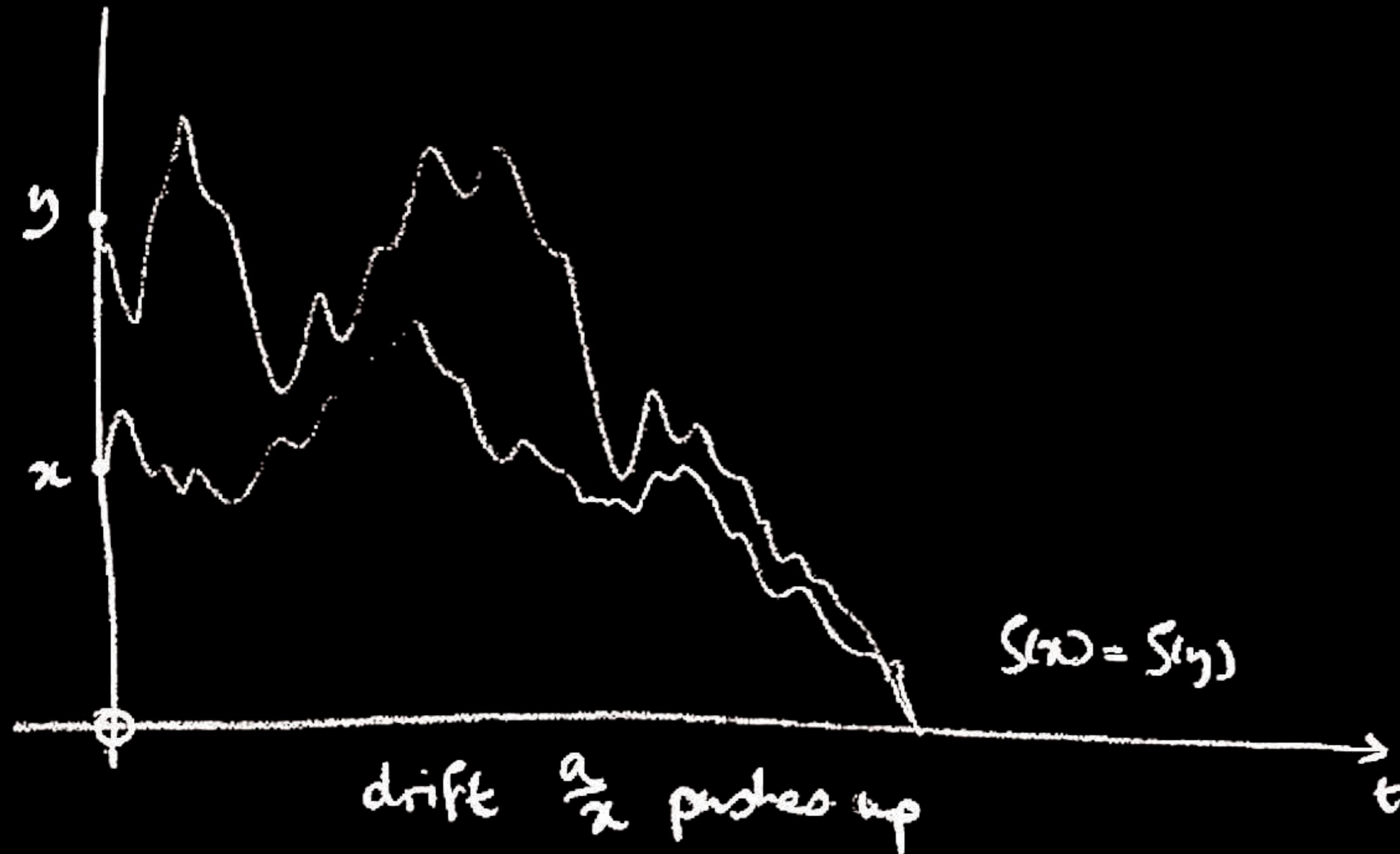
$$dX_t = dB_t + \frac{\alpha}{X_t} dt, \quad X_0 = x$$

Then, for all $x, y \in (0, \infty)$ with $x < y$,

- for $\alpha \in (0, \frac{1}{4}]$, $P(\zeta(x) < \zeta(y) < \infty) = 1$;
- for $\alpha \in (\frac{1}{4}, \frac{1}{2})$, $P(\zeta(x) < \infty) = 1$, $P(\zeta(x) < \zeta(y)) = \phi\left(\frac{y-x}{y}\right)$;
- for $\alpha \in [\frac{1}{2}, \infty)$, $P(\zeta(x) < \infty) = 0$.

Here, for $\alpha \in (\frac{1}{4}, \frac{1}{2})$, $\Theta \in [0, 1]$, ϕ is given by

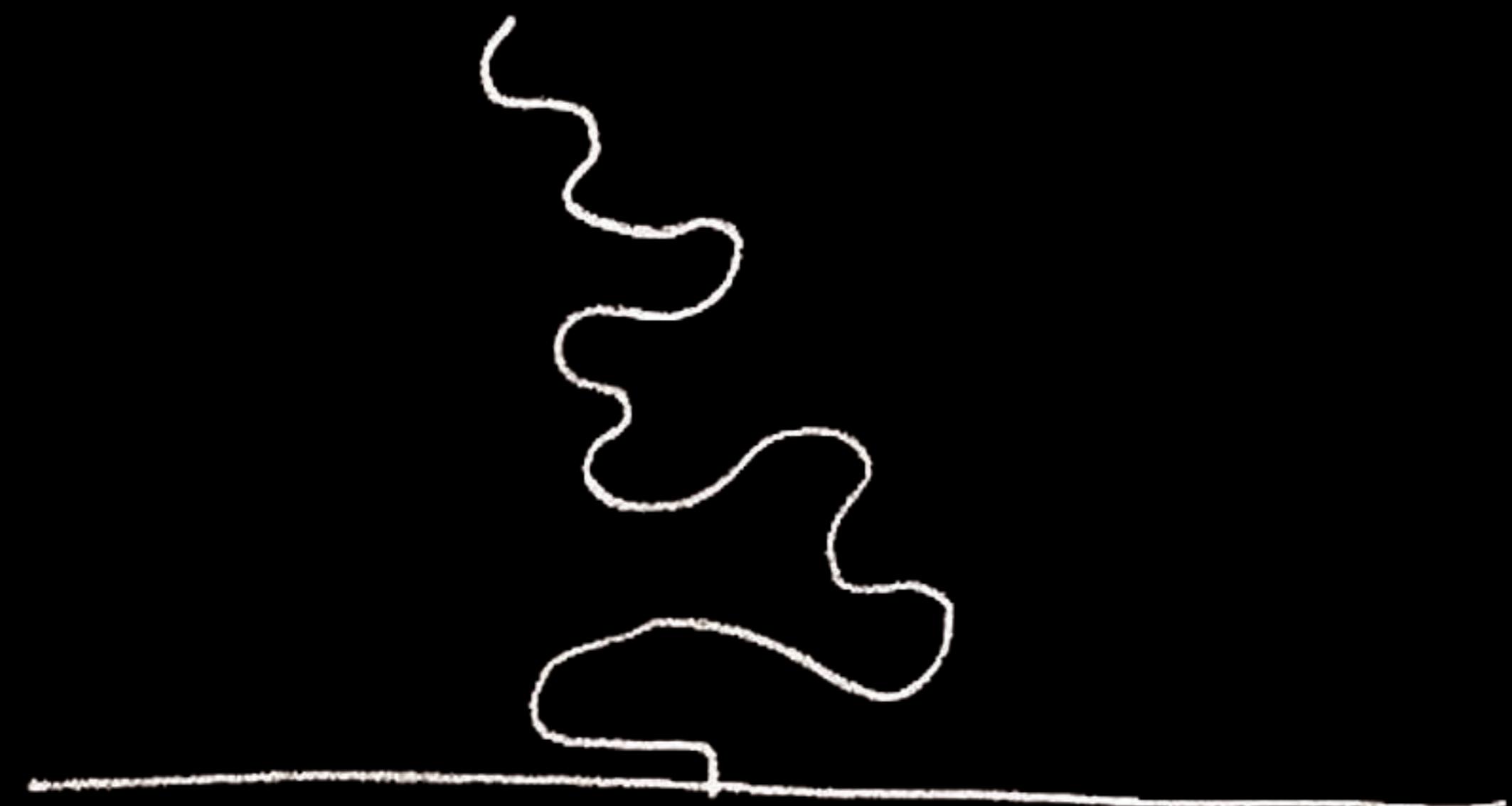
$$\phi(\Theta) \propto \int_0^\Theta \frac{du}{u^{2+4\alpha}(1-u)^{2\alpha}}, \quad \phi(1) = 1.$$



Proposition 6.2

Let γ be an SLE(k), with $k \in [0, 4]$.

Then $\gamma(0, \infty) \subseteq \mathbb{H}$ and γ is a simple curve, almost surely.



Proposition 6.3

Let γ be an SLE(K), with $K \in [0, 4]$.

Then $\gamma_t \rightarrow \infty$ as $t \rightarrow \infty$, almost surely.

Proposition 6.4

Let γ be an SLE(K), with $K \in (4, 8)$.

Then γ is neither simple, nor space-filling.

but $\text{dist}(0, H_t) \rightarrow \infty$ as $t \rightarrow \infty$.



This behaviour is
called swallowing

Proposition 6.5

Let γ be an SLE(k), with $k \in [8, \infty)$.

Then, almost surely, $\gamma[0, \infty) = \mathbb{H}$ and $\gamma_t \rightarrow \infty$ as $t \rightarrow \infty$.