## 13 Observability

We introduce the notion of observability for deterministic linear systems.

Consider the system

$$x_{n+1} = Ax_n, \quad y_{n+1} = Cx_n, \quad n \ge 0.$$

Here the state x takes values in  $\mathbb{R}^d$ , the observation y takes values in  $\mathbb{R}^p$ , and A and C are matrices of appropriate dimensions. We say that the system is observable in *n*-steps if  $y_1, \ldots, y_n$  determine uniquely the initial state  $x_0$ , for all  $x_0 \in \mathbb{R}^d$ . It is observable if it is observable in *n*-steps for some  $n \ge 1$ . Note that

$$\begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} = N_n x_0, \quad N_n = \begin{pmatrix} C \\ CA \\ \vdots \\ CA^{n-1} \end{pmatrix},$$

so the system is observable in *n*-steps if and only if  $\operatorname{rank}(N_n) = d$ . Hence, by the Cayley–Hamilton theorem, the system is observable if and only if  $\operatorname{rank}(N_d) = d$ .

The continuous-time system

$$\dot{x}_t = Ax_t, \quad \dot{y}_t = Cx_t, \quad y_0 = 0, \quad t \ge 0$$

is observable in time t if  $(y_s)_{0 \leq s \leq t}$  determines uniquely the initial state  $x_0$ , for all  $x_0 \in \mathbb{R}^d$ . Since

$$\left(\frac{d}{dt}\right)^n \bigg|_{t=0} y_t = CA^{n-1}x_0, \quad n \ge 1,$$

it is clear that, for any t > 0, the condition  $\operatorname{rank}(N_d) = d$  is sufficient for observability in time t. On the other hand, if  $\operatorname{rank}(N_d) \leq d-1$ , then there exists  $x_0 \in \mathbb{R}^d \setminus \{0\}$  such that  $CA^n x_0 = 0$  for  $n = 0, 1, \ldots, d-1$ , and hence for all n by Cayley–Hamilton. Hence

$$y_t = \int_0^t C e^{sA} x_0 ds = 0$$

for all  $t \ge 0$  and we cannot distinguish  $x_0$  from 0. The condition  $\operatorname{rank}(N_d) = d$  is thus equivalent to observability (in any time t > 0).

**Example (The sum of two populations).** Suppose  $\dot{x}_t = \lambda x_t$ ,  $\dot{z}_t = \mu z_t$  and we observe  $y_t = x_t + z_t$ . Can we determine  $x_0$  and  $z_0$ ?. In this case

$$A = \begin{pmatrix} \lambda & 0 \\ 0 & \mu \end{pmatrix}, \quad C = \begin{pmatrix} 1 & 0 \end{pmatrix}, \quad N_2 = \begin{pmatrix} 1 & 1 \\ \lambda & \mu \end{pmatrix}.$$

So we can determine  $x_0$  and  $z_0$ , provided  $\lambda \neq \mu$ . Even though we are provided with the extra information  $x_0 + z_0$ , if  $\lambda = \mu$ , we will have  $y_t = (x_0 + z_0)e^{\lambda t}$ , so we can never recover  $x_0$  alone.

**Example (Radioactive decay).** Suppose atoms of element 1 can decay in two ways, to atoms of element 2 at rate  $\alpha$  and to atoms of element 3 at rate  $\beta$ . Suppose that atoms of element 2 also decay to atoms of element 3, at rate  $\gamma$ . We observe the number of atoms of element 3. Can we determine the initial numbers of atoms of elements 1 and 2?

Here we have the system

$$\dot{x}_{t}^{1} = -(\alpha + \beta)x_{t}^{1}, \quad x_{t}^{2} = \alpha x_{t}^{1} - \gamma x_{t}^{2}, \quad \dot{x}_{t}^{3} = \beta x_{t}^{1} + \gamma x_{t}^{2},$$

 $\mathbf{SO}$ 

$$A = \begin{pmatrix} -\alpha - \beta & 0 & 0 \\ \alpha & -\gamma & 0 \\ \beta & \gamma & 0 \end{pmatrix}, C = \begin{pmatrix} 0 & 0 & 1 \end{pmatrix}, N_3 = \begin{pmatrix} C \\ CA \\ CA^2 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 1 \\ \beta & \gamma & 0 \\ \alpha\gamma - \beta(\alpha + \beta) & -\gamma^2 & 0 \end{pmatrix}.$$

Note that det  $N_3 = \gamma(\alpha + \beta)(\gamma - \beta)$ , so the system is observable if  $\gamma > 0, \alpha + \beta > 0$  and  $\beta \neq \gamma$ . It is easy to see that it is not so otherwise.