# LOCALITY OF CONNECTIVE CONSTANTS, I. TRANSITIVE GRAPHS 

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#### Abstract

The connective constant $\mu(G)$ of a quasi-transitive graph $G$ is the exponential growth rate of the number of self-avoiding walks from a given origin. We prove a locality theorem for connective constants, namely, that the connective constants of two graphs are close in value whenever the graphs agree on a large ball around the origin. The proof exploits a generalized bridge decomposition of self-avoiding walks, which is valid subject to the assumption that the underlying graph is quasi-transitive and possesses a so-called graph height function.


## 1. Introduction, and summary of results

There is a rich theory of interacting systems on infinite graphs. The probability measure governing a process has, typically, a continuously varying parameter, $p$ say, and there is a singularity at some 'critical point' $p_{c}$. The numerical value of $p_{c}$ depends in general on the choice of underlying graph $G$, and a significant part of the associated literature is directed towards estimates of $p_{\mathrm{c}}$ for different graphs. In most cases of interest, $p_{\mathrm{c}}$ depends on the large-scale properties of $G$, rather than on the geometry of some bounded domain only. This leads to the question of 'locality': to what degree is the value of $p_{c}$ determined by knowledge of a bounded domain of $G$ ?

The purpose of the current paper is to present a locality theorem (namely, Theorem 5.1) for the connective constant $\mu(G)$ of the graph $G$. A self-avoiding walk (SAW) is a path that visits no vertex more than once. SAWs were introduced in the study of long-chain polymers in chemistry (see, for example, the 1953 volume of Flory, [13]), and their theory has been much developed since (see the book of Madras and Slade, [30], and the recent review [2]). If the underlying graph $G$ has some periodicity, the number of $n$-step SAWs from a given origin grows exponentially with some growth rate $\mu(G)$ called the connective constant of the graph $G$.

There are only few graphs $G$ for which the numerical value of $\mu(G)$ is known exactly, and a substantial part of the literature on SAWs is devoted to inequalities

[^0]for $\mu(G)$. The current paper may be viewed in this light, as a continuation of the series of papers on the broad topic of connective constants of transitive graphs by the same authors, see [16, 17, 18, 19].

The main result (Theorem 5.1) of this paper is as follows. Let $G, G^{\prime}$ be infinite, vertex-transitive graphs, and write $S_{K}(v, G)$ for the $K$-ball around the vertex $v$ in $G$. If $S_{K}(v, G)$ and $S_{K}\left(v^{\prime}, G^{\prime}\right)$ are isomorphic as rooted graphs, then

$$
\begin{equation*}
\left|\mu(G)-\mu\left(G^{\prime}\right)\right| \leq \epsilon_{K}(G) \tag{1.1}
\end{equation*}
$$

where $\epsilon_{K}(G) \rightarrow 0$ as $K \rightarrow \infty$. (A related result holds for quasi-transitive graphs.)
This is proved subject to a certain condition on the graphs $G, G^{\prime}$, namely that they support so-called 'graph height functions' (see Section 3 for the definition of a graph height function). The existence of graph height functions permits the use of a 'bridge decomposition' of SAWs (in the style of the work of Hammersley and Welsh [25]), and this leads in turn to computable sequences that converge to $\mu(G)$ from above and below, respectively. The locality result of (1.1) may be viewed as a resolution of a conjecture of Benjamini, [3, Conj. 2.3], made independently of the work reported here.

A class of vertex-transitive graphs of special interest is provided by the Cayley graphs of finitely presented groups. Cayley graphs have algebraic as well as geometric structure, and this allows a deeper investigation of locality and of graph height functions. The corresponding investigation is reported in the companion paper [20] where, in particular, we present a method for the construction of a graph height function via a suitable harmonic function on the graph.

The locality question for percolation was approached by Benjamini, Nachmias, and Peres [4] for tree-like graphs. Let $G$ be vertex-transitive with degree $d+1$. It is elementary that the percolation critical point satisfies $p_{c} \geq 1 / d$ (see [7, Thm 7]), and an asymptotically equivalent upper bound for $p_{c}$ was developed in [4] for graphs with degree $d+1$ and large girth. In recent work of Martineau and Tassion [31], a locality result has been proved for percolation on abelian graphs. The proof extends the methods and conclusions of [21], where it is proved that the slab critical points converge to $p_{\mathrm{c}}\left(\mathbb{Z}^{d}\right)$, in the limit as the slabs become infinitely 'fat'. (A related result for connective constants is included here at Example 5.3.)

We are unaware of a locality theorem for the critical temperature $T_{\mathrm{c}}$ of the Ising model. Of the potentially relevant work on the Ising model to date, we mention [6, 8, 28].

This paper is organized as follows. Relevant background and notation is described in Section 2. The concept of a graph height function is presented in Section 3, where examples are included of infinite graphs with graph height functions, and a sufficient condition is presented in Theorem 3.4 for the existence of a graph height function. Bridges and the bridge constant are defined in Section 4, and it is proved in

Theorem 4.2 that the bridge constant equals the connective constant whenever there exists a graph height function. The main 'locality theorem' is given at Theorem 5.1. Theorem 5.2 is an application of the locality theorem in the context of a sequence of quotient graphs; this parallels the Grimmett-Marstrand theorem [21] for percolation on slabs, but with the underlying lattice replaced by a transitive graph with a graph height function. Sections 6 and 7 contain the proofs of Theorems 3.4 and 4.2.

## 2. Notation and background

The graphs $G=(V, E)$ considered here are generally assumed to be infinite, connected, and also simple, in that they have neither loops nor multiple edges (we shall relax this for the quotient graph $G / \mathcal{H}$ of Section 3). An undirected edge $e$ with endpoints $u, v$ is written as $e=\langle u, v\rangle$, and if directed from $u$ to $v$ as $[u, v\rangle$. If $\langle u, v\rangle \in E$, we call $u$ and $v$ adjacent and write $u \sim v$. The set of neighbours of $v \in V$ is denoted $\partial v$. When used in the context of directed graphs, the words 'directed' and 'oriented' are synonyms.

Loops and multiple edges have been excluded for cosmetic reasons only. A SAW can traverse no loop, and thus loops may be removed without changing the connective constant. The same proofs are valid in the presence of multiple edges. When there are multiple edges, we are effectively considering SAWs on a weighted simple graph, and indeed our results are valid for edge-weighted graphs with strictly positive weights, and for counts of SAWs in which the contribution of a given SAW is the product of the weights of the edges therein.

The degree of vertex $v$ is the number of edges incident to $v$, and $G$ is called locally finite if every vertex-degree is finite. The graph-distance between two vertices $u, v$ is the number of edges in the shortest path from $u$ to $v$, denoted $d_{G}(u, v)$.

The automorphism group of the graph $G=(V, E)$ is denoted Aut $(G)$. A subgroup $\Gamma \leq \operatorname{Aut}(G)$ is said to act transitively on $G$ (or on its vertex-set $V$ ) if, for $v, w \in V$, there exists $\gamma \in \Gamma$ with $\gamma v=w$. It is said to act quasi-transitively if there is a finite set $W$ of vertices such that, for $v \in V$, there exist $w \in W$ and $\gamma \in \Gamma$ with $\gamma v=w$. The graph is called (vertex-)transitive (respectively, quasi-transitive) if Aut $(G)$ acts transitively (respectively, quasi-transitively). For a subgroup $\mathcal{H} \leq \operatorname{Aut}(G)$ and a vertex $v \in V$, the orbit of $v$ under $\mathcal{H}$ is written $\mathcal{H} v$. The number of such orbits is written as $|G / \mathcal{H}|$.

A walk $w$ on $G$ is an alternating sequence $w_{0} e_{0} w_{1} e_{1} \cdots e_{n-1} w_{n}$ of vertices $w_{i}$ and edges $e_{i}=\left\langle w_{i}, w_{i+1}\right\rangle$. We write $|w|=n$ for the length of $w$, that is, the number of edges in $w$. The walk $w$ is called closed if $w_{0}=w_{n}$. A cycle is a closed walk $w$ satisfying $w_{i} \neq w_{j}$ for $1 \leq i<j \leq n$.

An $n$-step self-avoiding walk (SAW) on $G$ is a walk containing $n$ edges no vertex of which appears more than once. Let $\sigma_{n}(v)$ be the number of $n$-step SAWs starting
at $v \in V$. Let $\Sigma_{n}(v)$ be the set of $n$-step SAWs starting at $v$, with cardinality $\sigma_{n}(v):=\left|\Sigma_{n}(v)\right|$, and let

$$
\begin{equation*}
\sigma_{n}=\sigma_{n}(G):=\sup \left\{\sigma_{n}(v): v \in V\right\} \tag{2.1}
\end{equation*}
$$

We have in the usual way (see $[24,30]$ ) that

$$
\begin{equation*}
\sigma_{m+n} \leq \sigma_{m} \sigma_{n} \tag{2.2}
\end{equation*}
$$

whence the connective constant

$$
\mu=\mu(G):=\lim _{n \rightarrow \infty} \sigma_{n}^{1 / n}
$$

exists, and furthermore

$$
\begin{equation*}
\sigma_{n} \geq \mu^{n}, \quad n \geq 0 \tag{2.3}
\end{equation*}
$$

Hammersley [23] proved that, if $G$ is quasi-transitive, then

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \sigma_{n}(v)^{1 / n}=\mu, \quad v \in V \tag{2.4}
\end{equation*}
$$

We select a vertex of $G$ and call it the identity or origin, denoted 1. Further notation will be introduced when needed. The concept of a 'graph height function' is explained in the next section, and that leads in Section 4 to the definition of a 'bridge'.

The set of integers is written $\mathbb{Z}$, the natural numbers as $\mathbb{N}$, and the rationals as $\mathbb{Q}$.

## 3. Quasi-Transitive graphs and graph height functions

We consider quasi-transitive graphs with certain properties, and begin with some notation. Let $G=(V, E)$ be an infinite, connected, quasi-transitive, locally finite, simple graph.
Definition 3.1. A graph height function on $G$ is a function $h: V \rightarrow \mathbb{Z}$ such that:
(a) $h(\mathbf{1})=0$,
(b) there exists a subgroup $\mathcal{H} \leq \operatorname{Aut}(G)$ acting quasi-transitively on $G$ such that $h$ is $\mathcal{H}$-difference-invariant in the sense that

$$
h(\alpha v)-h(\alpha u)=h(v)-h(u), \quad \alpha \in \mathcal{H}, u, v \in V
$$

(c) for $v \in V$, there exist $u, w \in \partial v$ such that $h(u)<h(v)<h(w)$.

The expression 'graph height function' is chosen in contrast to the 'group height function' of [20]. It is explained in [20] that a group height function of a finitely presented group is a graph height function of its Cayley graph, but not vice versa.

For a given graph height function $h$, we may select a corresponding group of automorphisms denoted $\mathcal{H}=\mathcal{H}(h)$, and we shall sometimes refer to the pair $(h, \mathcal{H})$
as the graph height function. Associated with the pair $(h, \mathcal{H})$ are two integers $d, r$ which will play roles in the following sections and which we define next. Let

$$
\begin{equation*}
d=d(h)=\max \{|h(u)-h(v)|: u, v \in V, u \sim v\} . \tag{3.1}
\end{equation*}
$$

If $\mathcal{H}$ acts transitively, we set $r=0$. Assume $\mathcal{H}$ does not act transitively, and let $r=r(h, \mathcal{H})$ be the least integer such that the following holds. For $u, v \in V$ in different orbits of $\mathcal{H}$, there exist $u^{\prime} \in \mathcal{H} u, v^{\prime} \in \mathcal{H} v$ with $\left|u^{\prime}-v^{\prime}\right| \leq r$ such that: (i) $h\left(u^{\prime}\right)<h\left(v^{\prime}\right)$, and (ii) there is a SAW $\nu\left(u^{\prime}, v^{\prime}\right)$ from $u^{\prime}$ to $v^{\prime}$ all of whose vertices $x$, other than its endvertices, satisfy $h\left(u^{\prime}\right)<h(x)<h\left(v^{\prime}\right)$. The following proposition is proved at the end of this section.
Proposition 3.2. Let $(h, \mathcal{H})$ be a graph height function on the graph $G$. Then

$$
0 \leq r(h, \mathcal{H}) \leq(N-1)(2 d+1)+2
$$

where $N=|G / \mathcal{H}|$ and $d$ is given by (3.1).
Not every quasi-transitive graph has a graph height function, since (c), above, fails if $G$ has a cut-vertex whose removal breaks $G$ into an infinite and a finite part. We do not have a useful necessary and sufficient condition for the existence of a graph height function, and we pose the following more restrictive question.
Question 3.3. Does every infinite, connected, transitive, locally finite, simple graph have a graph height function?

In [20] a related (but different) question is answered in the negative in the context of Cayley graphs of finitely generated groups, by consideration of the Higman group. It may be the case that the Cayley graph of the Higman group has no graph height function.

A sufficient condition for the existence of a graph height function on a transitive graph $G$ is provided in the forthcoming Theorem 3.4. The cycle space $\mathcal{C}=\mathcal{C}(G)$ of $G$ is the vector space over the field $\mathbb{Z}_{2}$ generated by the cycles (see, for example, [9]). Let $\mathcal{H} \leq \operatorname{Aut}(G)$ act quasi-transitively on $G$. The cycle space is said to be finitely generated (with respect to $\mathcal{H}$ ) if there is a finite set $\mathcal{B}(\mathcal{C})$ of cycles which, taken together with their images under $\mathcal{H}$, form a basis for $\mathcal{C}(G)$. If this holds, $\mathcal{C}$ may be viewed as a finitely generated $\mathcal{H}$-module (see [22]). It is elementary that the Cayley graph of any finitely presented group $\Gamma$ has this property (with respect to $\Gamma$ ), since its cycle space is generated by the cycles derived from the action of the group on the conjugates of the relators. As examples of locally finite, transitive graphs whose cycle spaces are not finitely generated, we propose the Cayley graphs of groups that are finitely generated but not finitely presented, such as the interesting examples of Grigorchuk [15] and Dunwoody [11].

We remind the reader of the definition of a quotient graph. Let $\mathcal{H}$ be a subgroup of $\operatorname{Aut}(G)$. We denote by $\vec{G}=(\bar{V}, \vec{E})$ the (directed) quotient graph $G / \mathcal{H}$ constructed
as follows. The vertex-set $\bar{V}$ comprises the orbits $\bar{v}:=\mathcal{H} v$ as $v$ ranges over $V$. For $v, w \in V$, we place $|\partial v \cap \bar{w}|$ directed edges from $\bar{v}$ to $\bar{w}$, and we write $\bar{v} \sim \bar{w}$ if $|\partial v \cap \bar{w}| \geq 1$ and $\bar{v} \neq \bar{w}$. If $\bar{v}=\bar{w}$, an edge from $\bar{v}$ to $\bar{w}$ is a directed 'loop', and the word 'loop' is used only in this context in this paper. By [19, Lemma 3.6], the number $|\partial v \cap \bar{w}|$ is independent of the choice of $v \in \bar{v}$. When convenient, we shall work with the undirected simple graph derived from this directed multigraph by ignoring any loops, orientations, and multiplicities of edges.

The group $\mathcal{H}$ is called symmetric if

$$
\begin{equation*}
|\partial v \cap \bar{w}|=|\partial w \cap \bar{v}|, \quad v, w \in V \tag{3.2}
\end{equation*}
$$

Sufficient conditions for (3.2) are found in [19, Lemma 3.10]. If $\mathcal{H}$ is symmetric, we may define the undirected graph $\bar{G}=(\bar{V}, \bar{E})$ by placing $|\partial v \cap \bar{w}|$ parallel edges between $\bar{v}$ and $\bar{w}$, and $|\partial v \cap \bar{v}|$ loops at $v$.

Any (directed) walk $\pi$ on $G$ induces a (directed) walk $\vec{\pi}$ on $\vec{G}$, and we say that $\pi$ projects onto $\vec{\pi}$. For a walk $\vec{\pi}$ on $\vec{G}$, there exists a walk $\pi$ on $G$ that projects onto $\vec{\pi}$, and we say that $\vec{\pi}$ lifts to $\pi$. Note that a cycle of $G$ projects onto a closed walk of $\vec{G}$, which may or may not be a cycle.

Theorem 3.4. Let $G=(V, E)$ be an infinite, connected, transitive, locally finite, simple graph. Suppose there exist a subgroup $\Gamma \leq \operatorname{Aut}(G)$ acting transitively on $V$, and a normal subgroup $\mathcal{H} \unlhd \Gamma$ with index satisfying $[\Gamma: \mathcal{H}]<\infty$, such that the following hold:
(a) $\mathcal{H}$ is symmetric,
(b) $\mathcal{C}(G)$ is finitely generated (with respect to $\mathcal{H}$ ) by a set $\mathcal{B}$ of cycles,
(c) every directed $B \in \mathcal{B}$ projects onto a cycle of $\vec{G}$.

Then $G$ has a graph height function of the form $(h, \mathcal{H})$.
The idea of the proof, which is found in Section 6 and illustrated in Example 6.3, is to construct a suitable function on the quotient graph $\vec{G}$, and to export this to a graph height function $h$ on $G$ via the action of $\mathcal{H}$. It may be seen from the proof that $d(h) \leq D_{e}$ and $r(h, \mathcal{H}) \leq R_{e}$, for some $D_{e}, R_{e}$ depending only on the number $e$ of edges of $\bar{G}$.

In [20] is presented an alternative version of Theorem 3.4 which, on the one hand, is more restrictive in that it makes the further assumption that $\mathcal{H}$ is unimodular, but, on the other hand, has an interesting and informative proof using the language of harmonic functions and random walk. The restriction of unimodularity is satisfied automatically in the context of Cayley graphs, which are the objects of study of the associated article [20].

Here are several examples of transitive graphs with graph height functions.
(a) The hypercubic lattice $\mathbb{Z}^{n}$ with, say, $h\left(x_{1}, x_{2}, \ldots, x_{n}\right)=x_{1}$. With $\mathcal{H}$ the set of translations of $\mathbb{Z}^{n}$, we have $d(h)=1$ and $r(h)=0$.
(b) The $d$-regular tree $T$ may be drawn as in Figure 3.1. We fix a ray $\omega$ of $T$, and we 'suspend' $T$ from $\omega$ as in the figure. A vertex on $\omega$ is designated as identity 1 and is given height 0 , and other vertices have heights as indicated. The set $\mathcal{H}$ is the subgroup of automorphisms that fix $\omega$, and it acts transitively. We have $d=1$ and $r=0$.


Figure 3.1. The 3-regular tree with the 'horocyclic' height function.
(c) There follow three examples of Cayley graphs of finitely presented groups (readers are referred to [20] for further information on Cayley graphs). The discrete Heisenberg group

$$
\Gamma=\left\{\left(\begin{array}{ccc}
1 & x & z \\
0 & 1 & y \\
0 & 0 & 1
\end{array}\right): x, y, z \in \mathbb{Z}\right\}
$$

has generator set $S=\left\{s_{1}, s_{2}, s_{3}, s_{1}^{\prime}, s_{2}^{\prime}, s_{3}^{\prime}\right\}$ where

$$
s_{1}=\left(\begin{array}{lll}
1 & 1 & 0 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{array}\right) \quad s_{2}=\left(\begin{array}{lll}
1 & 0 & 0 \\
0 & 1 & 1 \\
0 & 0 & 1
\end{array}\right) \quad s_{3}=\left(\begin{array}{lll}
1 & 0 & 1 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{array}\right)
$$

and relator set

$$
R=\left\{s_{1} s_{1}^{\prime}, s_{2} s_{2}^{\prime}, s_{3} s_{3}^{\prime}\right\} \cup\left\{s_{1} s_{2} s_{1}^{\prime} s_{2}^{\prime} s_{3}^{\prime}, s_{1} s_{3} s_{1}^{\prime} s_{3}^{\prime}, s_{2} s_{3} s_{2}^{\prime} s_{3}^{\prime}\right\}
$$

Consider its Cayley graph. To a directed edge of the form $\left[v, v s_{1}\right\rangle$ (respectively, $\left.\left[v, v s_{1}^{\prime}\right\rangle\right)$ we associate the height difference 1 (respectively, -1 ), and to all other edges height difference 0 . We have $d=1$ and $r=0$. The height $h(v)$ of vertex $v$ is given by adding the height differences along any directed path from $\mathbf{1}$ to $v$, where $\mathbf{1}$ is the identity of the group.
(d) The square/octagon lattice of Figure 3.2 is the Cayley graph of the group with generators $s_{1}, s_{2}, s_{3}$ and relators $\left\{s_{1}^{2}, s_{2}^{2}, s_{3}^{2}, s_{1} s_{2} s_{1} s_{2}, s_{1} s_{3} s_{2} s_{3} s_{1} s_{3} s_{2} s_{3}\right\}$. It has no graph height function with $\mathcal{H}$ acting transitively. There are numerous ways to define a height function with quasi-transitive $\mathcal{H}$, of which we mention one. Let $\mathcal{H}$ be the automorphism subgroup generated by the shifts that map 1 to $\mathbf{1}^{\prime}$ and $\mathbf{1}^{\prime \prime}$, respectively, and let the graph height function be as in the figure. We have $d=1$ and $r=5$.


Figure 3.2. The square/octagon lattice. The subgroup $\mathcal{H}$ is generated by the shifts $\tau, \tau^{\prime \prime}$ that map $\mathbf{1}$ to $\mathbf{1}^{\prime}$ and $\mathbf{1}^{\prime \prime}$, respectively, and $h(v)$ measures the horizontal displacement of $v$ as marked.
(e) The hexagonal lattice of Figure 3.3 is the Cayley graph of a finitely presented group. It possesses a graph height function $h$ with $\mathcal{H}$ acting transitively, as follows. Let $\mathcal{T}$ be the set of automorphisms of the lattice that act by translation of the figure, and let $\rho$ be reflection in the vertical line as indicated there. With the heights as given in the figure, we take $\mathcal{H}$ to be the group generated by $\mathcal{T}$ and $\rho$. This is an example for which $\mathcal{H}$ is not torsion-free, and we have $d=1$ and $r=0$. Since $\mathcal{T}$ acts quasi-transitively, one may also work with $\mathcal{H}:=\mathcal{T}$, in which case $r=1$.
(f) The Diestel-Leader graphs $\mathrm{DL}(m, n)$ with $m \neq n$ were proposed in [10] as candidates for transitive graphs that are quasi-isometric to no Cayley graph, and this conjecture was proved in [12] (see [11] for a further example). They arise through a certain combination (details of which are omitted here) of a $(m+1)$-regular tree and a $(n+1)$-regular tree, and the horocyclic graph height function of either tree provides a graph height function for the combination. We have $d=1$ and $r=0$.


Figure 3.3. The hexagonal lattice. The heights of vertices are as marked, and $\rho$ denotes reflection in the dashed line.

Proof of Proposition 3.2. Let $(h, \mathcal{H})$ be as in Definition 3.1, and assume that $\mathcal{H}$ acts quasi-transitively but not transitively. For $v, w \in V$ in distinct orbits of $\mathcal{H}$, we write $v \rightarrow w$ if there exist $v^{\prime} \in \mathcal{H} v, w^{\prime} \in \mathcal{H} w$ such that (i) $h\left(v^{\prime}\right)<h\left(w^{\prime}\right)$, and (ii) there is a SAW $\nu=\left(\nu_{0}, \nu_{1}, \ldots, \nu_{m}\right)$ with $\nu_{0}=v^{\prime}, \nu_{m}=w^{\prime}$ and $h\left(v^{\prime}\right)<h\left(\nu_{j}\right)<h\left(w^{\prime}\right)$ for $1 \leq j<m$. We prove next that $v \rightarrow w$ for all such $v, w \in V$. Since $\mathcal{H}$ has only finitely many orbits, this will imply that $r(h, \mathcal{H})<\infty$.

Let $\bar{G}=(\bar{V}, \bar{E})$ be the simple, undirected quotient graph obtained from $\vec{G}$ by placing a single undirected edge between $\bar{a}, \bar{b} \in \bar{V}$ if and only if $\partial a \cap \bar{b} \neq \varnothing$. For given $u \in V, \bar{G}$ lifts to a connected subgraph $G_{u}$ of $G$ which contains $u$ as well as exactly one member of each orbit of $\mathcal{H}$. Since $\bar{G}$ is connected, it has a spanning tree $\bar{T}$ that lifts to a spanning tree $T_{u}$ of $G_{u}$. With $N=|\bar{V}|=|G / \mathcal{H}|$, the tree $T_{u}$ has $N-1$ edges. Let

$$
\Delta_{u}=\max \left\{|h(a)-h(b)|: a, b \in G_{u}\right\} .
$$

By (3.1),

$$
\begin{equation*}
\left|\Delta_{u}\right| \leq(N-1) d, \quad u \in V \tag{3.3}
\end{equation*}
$$

For $v \in V$, there exists by Definition 3.1(c) a doubly infinite SAW $\pi(v)=\left(\pi_{j}(v)\right.$ : $j \in \mathbb{Z}$ ) with $\pi_{0}(v)=v$ and such that $h\left(\pi_{j}(v)\right)$ is strictly increasing in $j$. Since $h$ takes integer values,

$$
\begin{equation*}
h\left(\pi_{j+1}(v)\right)-h\left(\pi_{j}(v)\right) \geq 1, \quad j \in \mathbb{Z}, v \in V \tag{3.4}
\end{equation*}
$$

Let $v, w \in V$ be in distinct orbits of $\mathcal{H}$. Let $v^{\prime}=\pi_{R}(v)$ and $w^{\prime}=\pi_{-R}(w)$ where $R \geq 1$ will be chosen soon. Find $\alpha \in \mathcal{H}$ such that $\alpha v^{\prime} \in G_{w^{\prime}}$. Let $\nu$ be the walk obtained by following the sub-SAW of $\alpha \pi(v)$ from $\alpha v$ to $\alpha v^{\prime}$, followed by the sub-path of $T_{w^{\prime}}$ from $\alpha v^{\prime}$ to $w^{\prime}$, followed by the sub-SAW of $\pi(w)$ from $w^{\prime}$ to $w$. The length of $\nu$ is at most $2 R+N-1$.

By (3.4), we can pick $R$ sufficiently large that

$$
\begin{aligned}
h(\alpha v) & <\min \left\{h(a): a \in G_{w^{\prime}}\right\} \\
& \leq h\left(\alpha v^{\prime}\right), h\left(w^{\prime}\right) \\
& \leq \max \left\{h(a): a \in G_{w^{\prime}}\right\}<h(w)
\end{aligned}
$$

and indeed, by (3.3), it suffices that $R=(N-1) d+1$. By loop-erasure of $\nu$, we obtain a SAW $\nu^{\prime}=\left(\nu_{0}^{\prime}, \nu_{1}^{\prime}, \ldots, \nu_{m}^{\prime}\right)$ with $\nu_{0}^{\prime}=\alpha v, \nu_{m}^{\prime}=w$,

$$
\begin{equation*}
m \leq 2 R+N-1 \leq 2(N-1) d+2+(N-1) \tag{3.5}
\end{equation*}
$$

and $h\left(\nu_{0}^{\prime}\right)<h\left(\nu_{j}^{\prime}\right)<h\left(\nu_{m}^{\prime}\right)$ for $1 \leq j<m$. Therefore, $v \rightarrow w$ as required. The upper bound for $r$ follows from (3.5).

## 4. Bridges and the bridge constant

Assume that $G$ is quasi-transitive with graph height function $(h, \mathcal{H})$. The forthcoming definitions depend on the choice of pair $(h, \mathcal{H})$.

Let $v \in V$ and $\pi=\left(\pi_{0}, \pi_{1}, \ldots, \pi_{n}\right) \in \Sigma_{n}(v)$. We call $\pi$ a half-space $S A W$ if

$$
h\left(\pi_{0}\right)<h\left(\pi_{i}\right), \quad 1 \leq i \leq n
$$

and we write $c_{n}(v)$ for the number of half-space walks with initial vertex $v$. We call $\pi$ a bridge if

$$
\begin{equation*}
h\left(\pi_{0}\right)<h\left(\pi_{i}\right) \leq h\left(\pi_{n}\right), \quad 1 \leq i \leq n \tag{4.1}
\end{equation*}
$$

and a reversed bridge if (4.1) is replaced by

$$
h\left(\pi_{n}\right) \leq h\left(\pi_{i}\right)<h\left(\pi_{0}\right), \quad 1 \leq i \leq n
$$

The span of a SAW $\pi$ is defined as

$$
\operatorname{span}(\pi)=\max _{0 \leq i \leq n} h\left(\pi_{i}\right)-\min _{0 \leq i \leq n} h\left(\pi_{i}\right) .
$$

The number of $n$-step bridges from $v$ with span $s$ is denoted $b_{n, s}(v)$, and in addition

$$
b_{n}(v)=\sum_{s=0}^{\infty} b_{n, s}(v)
$$

is the total number of $n$-step bridges from $v$. Let

$$
\begin{equation*}
b_{n}=b_{n}(G):=\inf \left\{b_{n}(v): v \in V\right\} \tag{4.2}
\end{equation*}
$$

It is easily seen (as in [25]) that

$$
\begin{equation*}
b_{m+n} \geq b_{m} b_{n} \tag{4.3}
\end{equation*}
$$

from which we deduce the existence of the bridge constant

$$
\begin{equation*}
\beta=\beta(G)=\lim _{n \rightarrow \infty} b_{n}^{1 / n} \tag{4.4}
\end{equation*}
$$

satisfying

$$
\begin{equation*}
b_{n} \leq \beta^{n}, \quad n \geq 0 \tag{4.5}
\end{equation*}
$$

Proposition 4.1. Let $G=(V, E)$ be an infinite, connected, quasi-transitive, locally finite, simple graph possessing a height function $(h, \mathcal{H})$. Then

$$
\begin{equation*}
b_{n}(v)^{1 / n} \rightarrow \beta, \quad v \in V, \tag{4.6}
\end{equation*}
$$

and furthermore

$$
\begin{equation*}
b_{n}(v) \leq \beta^{n+r}, \quad n \geq 1, v \in V \tag{4.7}
\end{equation*}
$$

where $r=r(h, \mathcal{H})$ is given after (3.1).
Theorem 4.2. Let $G=(V, E)$ be an infinite, connected, quasi-transitive, locally finite, simple graph possessing a height function $h$. Then $\beta=\mu$.

This theorem extends that of Hammersley and Welsh [25] for lattices, and has as corollary that the value of the bridge constant is independent of the choice of pair $(h, \mathcal{H})$. The proof of the theorem is deferred to Section 7.

It is proved in [19] that systematic changes to a graph $G$ lead to a strict change in the value of its connective constant, and the question is posed there of whether one can establish a concrete numerical bound on the magnitude of the change of value. It is proved in [19, Thm 3.7] that this can be done whenever there exists a real sequence $\left(a_{n}\right)$ satisfying $a_{n} \uparrow \mu(G)$, and which can be calculated in finite time. For any graph $G$ satisfying the hypothesis of Theorem 4.2, we may take $a_{n}=b_{n}^{1 / n}$.

Proof of Proposition 4.1. Assume $G$ has graph height function $(h, \mathcal{H})$. If $G$ is transitive, the claim is trivial, so we assume $G$ is quasi-transitive but not transitive. For $v, w \in V$ with $w \notin \mathcal{H} v$, let $\nu(v, w)$ be a SAW from $v$ to some $w^{\prime} \in \mathcal{H} w$ with $h(v)<h\left(w^{\prime}\right)$, every vertex $x$ of which, other than its endvertices, satisfies $h(v)<h(x)<h\left(w^{\prime}\right)$. We may assume that the length $l(v, w)$ of $\nu(v, w)$ satisfies $l(v, w) \leq r$ for all such pairs $v, w$.

By counting bridges from the endvertices of $\nu(v, x)$ and $\nu(x, v)$, we obtain that

$$
b_{n}(v) \geq b_{n-l}(x) \geq b_{n-l-l^{\prime}}(v) \geq b_{n-2 r}(v)
$$

where $l=l(v, x)$ and $l^{\prime}=l(x, v)$, and we have used Definition 3.1(c) for the last inequality. The limit (4.6) follows by (4.4). Now choose $x \in V$ such that $b_{n+r}(x)=$ $b_{n+r}$, and assume $x \notin \mathcal{H} v$. Since $b_{n+l}(x) \leq b_{n+r}(x)$,

$$
b_{n}(v) \leq b_{n+l}(x) \leq b_{n+r}(x)=b_{n+r}
$$

and the final claim follows by (4.5).

## 5. Locality of connective constants

Let $\mathcal{G}$ be the set of all infinite, connected, quasi-transitive, locally finite, simple graphs. For $G \in \mathcal{G}$, we choose a vertex which we label $\mathbf{1}=\mathbf{1}_{G}$ and call the identity or origin of $G$. The sphere $S_{k}(v)=S_{k}(v, G)$, with centre $v$ and radius $k$, is the subgraph of $G$ induced by the set of its vertices within graph-distance $k$ of $v$. For $G, G^{\prime} \in \mathcal{G}$, we write $S_{k}(v, G) \simeq S_{k}\left(v^{\prime}, G^{\prime}\right)$ if there exists a graph-isomorphism from $S_{k}(v, G)$ to $S_{k}\left(v^{\prime}, G^{\prime}\right)$ that maps $v$ to $v^{\prime}$. We define the similarity function $K$ on $\mathcal{G} \times \mathcal{G}$ by

$$
K\left(G, G^{\prime}\right)=\max \left\{k: S_{k}\left(\mathbf{1}_{G}, G\right) \simeq S_{k}\left(\mathbf{1}_{G^{\prime}}, G^{\prime}\right)\right\}, \quad G, G^{\prime} \in \mathcal{G}
$$

and the corresponding distance-function $d\left(G, G^{\prime}\right)=2^{-K\left(G, G^{\prime}\right)}$. The corresponding metric space was introduced by Babai [1]; see also [5, 10].

For $D, R \in \mathbb{N}$, let $\mathcal{G}_{D, R}$ be the set of all $G \in \mathcal{G}$ which possess a graph height function $h$ satisfying $d(h) \leq D$ and $r(h) \leq R$. For a quasi-transitive graph $G$, we write $M=M(G)=|G / \operatorname{Aut}(G)|$ for the number of orbits under its automorphism group. The locality theorem for quasi-transitive graphs follows, with proof at the end of the section. The theorem may be regarded as a partial resolution of a question of Benjamini, [3, Conj. 2.3], which was posed independently of the work reported here.

Theorem 5.1 (Locality theorem for connective constants). Let $G, G^{\prime} \in \mathcal{G}$ with $K=K\left(G, G^{\prime}\right)$. Write $M=M(G)$ and $M^{\prime}=M\left(G^{\prime}\right)$.
(a) There exist $\epsilon_{k}=\epsilon_{k}\left(G, M^{\prime}\right)$, satisfying $0<\epsilon_{k} \downarrow 0$ as $k \rightarrow \infty$, such that

$$
\begin{equation*}
\mu\left(G^{\prime}\right) \leq \mu(G)+\epsilon_{K} \tag{5.1}
\end{equation*}
$$

(b) Let $D, R \geq 1$ and $G^{\prime} \in \mathcal{G}_{D, R}$. There exists a constant $B=B(D, R) \in(0, \infty)$ such that, for $K>M^{\prime}-1$,

$$
\begin{equation*}
\frac{\mu(G)}{f\left(K-M^{\prime}+1\right)} \leq \beta\left(G^{\prime}\right)=\mu\left(G^{\prime}\right) \tag{5.2}
\end{equation*}
$$

where $f(x)=\left[B x^{3} e^{B \sqrt{x}}\right]^{1 / x}$.
(c) Let $D, R \geq 1$. Let $G \in \mathcal{G}$ and $G_{m} \in \mathcal{G}_{D, R}$ for $m \geq 1$ be such that $K\left(G, G_{m}\right)-$ $M\left(G_{m}\right) \rightarrow \infty$ as $m \rightarrow \infty$. Then $\mu\left(G_{m}\right) \rightarrow \mu(G)$.

When $G$ is transitive, $M(G)=1$ and one may take $R=0$. The statement of the theorem is thus simpler when restricted to transitive graphs.

The following application of Theorem 5.1 is prompted in part by a result in percolation theory. Let $p_{c}(G)$ be the critical probability of either bond or site percolation on an infinite graph $G$, and let $\mathbb{Z}^{d}$ be the $d$-dimensional hypercubic lattice with $d \geq 3$, and $S_{k}=\mathbb{Z}^{2} \times\{0,1, \ldots, k\}^{d-2}$. It was proved by Grimmett and Marstrand [21] that

$$
\begin{equation*}
p_{\mathrm{c}}\left(S_{k}\right) \rightarrow p_{\mathrm{c}}\left(\mathbb{Z}^{d}\right) \quad \text { as } k \rightarrow \infty \tag{5.3}
\end{equation*}
$$

Does a corresponding limit hold for connective constants? For simplicity, we consider this question for transitive graphs only.

Let $G \in \mathcal{G}$ and let $\Gamma$ be a subgroup of $\operatorname{Aut}(G)$ that acts transitively. For $m \geq 1$, let $\alpha_{m} \in \Gamma$ and let $\mathcal{A}_{m}$ be the normal subgroup of $\Gamma$ generated by $\alpha_{m}$. The group $\mathcal{A}_{m}$ gives rise to a quotient graph $G_{m}=G / \mathcal{A}_{m}$, which we regard as an undirected, simple graph. Since $\mathcal{A}_{m}$ is a normal subgroup of $\Gamma, \Gamma$ acts transitively on $G / \mathcal{A}_{m}$ (by [19, Remark 3.5]), whence $G_{m}$ is transitive.

Theorem 5.2. Let $D \geq 1$, and assume $G_{m}=G / \mathcal{A}_{m} \in \mathcal{G}_{D, 0}$ for all $m$, and further that $d_{G}\left(\mathbf{1}, \alpha_{m} \mathbf{1}\right) \rightarrow \infty$ as $m \rightarrow \infty$. Then $\mu\left(G_{m}\right) \rightarrow \mu(G)$ as $m \rightarrow \infty$.
Proof. The quotient graph is obtained from $G$ by identifying any two vertices $v \neq w$ with $w=\alpha v$ and $\alpha \in \mathcal{A}_{m}$. For such $v, w$, we have $d_{G}(v, w) \geq d_{G}\left(\mathbf{1}, \alpha_{m} \mathbf{1}\right)$. Therefore, $K\left(G, G_{m}\right) \geq \frac{1}{2} d_{G}\left(\mathbf{1}, \alpha_{m} \mathbf{1}\right)-1$, and the result follows by Theorem 5.1.
Example 5.3. Let $G$ be the hypercubic lattice $\mathbb{Z}^{n}$ with $n \geq 2$, and let $\Gamma$ be the set of its translations. Choose $v=\left(v_{1}, v_{2}, \ldots, v_{n}\right) \in \mathbb{Z}^{n}$ with $v \neq \mathbf{0}$, and let $\alpha_{v} \in \Gamma$ be the translation $w \mapsto w+v$. Let $p_{v}$ be a unit vector perpendicular to $v$, and let $k_{v}$ be the smallest positive integer such that $k_{v} p_{v}$ is a vector of integers. For $z \in \mathbb{Z}^{n}$, let $h_{v}(z)=z \cdot\left(k_{v} p_{v}\right)$, so that $\left(h_{v}, \Gamma\right)$ is a graph height function with $d\left(h_{v}\right) \leq k_{v}$ and $r\left(h_{v}\right)=0$.

Let $\mathcal{A}_{v}$ be the normal subgroup of $\Gamma$ generated by $\alpha_{v}$. In the notation of Theorem 5.2, we have that $\mu\left(G / \mathcal{A}_{v_{m}}\right) \rightarrow \mu(G)$ as $m \rightarrow \infty$, so long as the sequence ( $v_{m}$ ) satisfies $\left|v_{m}\right| \rightarrow \infty$ and $\limsup _{m \rightarrow \infty} d\left(h_{v_{m}}\right)<\infty$. This may be regarded as a version of the limit (5.3) with connective constants in place of critical percolation probabilities.
Proof of Theorem 5.1. Let $G$ be quasi-transitive with $M=M(G)$. Since the quotient graph $G / \operatorname{Aut}(G)$ is connected, $G$ has some connected subgraph $H$ containing 1 and comprising exactly one member of each orbit under $\operatorname{Aut}(G)$. Since $|H|=M$, $H$ has a spanning tree containing $M-1$ edges. Therefore, for $n \geq M-1$,

$$
\begin{equation*}
\sigma_{n}=\sigma_{n}(v) \text { for some } v \in H \tag{5.4}
\end{equation*}
$$

(a) Let $G, G^{\prime} \in \mathcal{G}$, and recall (2.3). Pick $\eta_{k}=\eta_{k}(G)$ such that $0<\eta_{k} \downarrow 0$ as $k \rightarrow \infty$ and

$$
\begin{equation*}
\mu(G)^{n} \leq \sigma_{n}(G) \leq\left(\mu(G)+\eta_{k}\right)^{n}, \quad n \geq k \tag{5.5}
\end{equation*}
$$

Since $K\left(G, G^{\prime}\right)=K$, we have that $S_{K}\left(\mathbf{1}_{G}, G\right) \simeq S_{K}\left(\mathbf{1}_{G^{\prime}}, G^{\prime}\right)$, and by (5.4)

$$
\begin{equation*}
\sigma_{K-S}\left(G^{\prime}\right)=\sigma_{K-S}(G) \tag{5.6}
\end{equation*}
$$

where $S=\max \left\{M, M^{\prime}\right\}-1$. By (5.5)-(5.6) and (2.2), for $r \geq 1$,

$$
\begin{aligned}
\sigma_{(K-S) r}\left(G^{\prime}\right) & \leq \sigma_{K-S}\left(G^{\prime}\right)^{r} \\
& =\sigma_{K-S}(G)^{r} \leq\left(\mu(G)+\eta_{K-S}\right)^{(K-S) r}
\end{aligned}
$$

We take $(K-S) r^{\text {th }}$ roots and let $r \rightarrow \infty$, to obtain that $\mu\left(G^{\prime}\right) \leq \mu(G)+\epsilon_{K}$, where $\epsilon_{K}=\eta_{K-S}$.
(b) Let $D, R \geq 1$ and $G^{\prime} \in \mathcal{G}_{D, R}$. By the forthcoming Proposition 7.3 and (5.5)(5.6), there exists $B=B(D, R)$ such that

$$
\begin{aligned}
\beta\left(G^{\prime}\right)^{K-S^{\prime}} & \geq \frac{\sigma_{K-S^{\prime}}\left(G^{\prime}\right)}{B\left(K-S^{\prime}\right)^{3} e^{B \sqrt{K-S^{\prime}}}} \\
& =\frac{\sigma_{K-S^{\prime}}(G)}{f\left(K-S^{\prime}\right)^{K-S^{\prime}}} \geq \frac{\mu(G)^{K-S^{\prime}}}{f\left(K-S^{\prime}\right)^{K-S^{\prime}}}
\end{aligned}
$$

where $S^{\prime}=M^{\prime}-1$. Therefore,

$$
\beta\left(G^{\prime}\right) \geq \frac{\mu(G)}{f\left(K-S^{\prime}\right)}
$$

By Theorem 4.2, $\mu\left(G^{\prime}\right)=\beta\left(G^{\prime}\right)$, and (5.2) is proved.
(c) This is immediate from part (b).

## 6. Proof of Theorem 3.4

Edges, walks, and cycles may sometimes be directed and sometimes undirected in the following proof. We use notation and words to distinguish between these two situations, and we hope our presentation is clear to the reader.

Since $\mathcal{H}$ is assumed symmetric (see (3.2)), we may define the undirected graph $\bar{G}=(\bar{V}, \bar{E})$. We consider $\vec{G}=(\bar{V}, \vec{E})$ as the directed graph obtained from $\bar{G}$ by replacing each edge $e \in \bar{E}$ by two edges with the same endpoints and opposite orientations, and we label such a pair as $\vec{e}$ and $-\vec{e}$. An oriented cycle of $\vec{G}$ is a cycle which may be followed consistently with its orientations.

We propose to construct a graph height function $h$ by (i) finding a 'difference' function $\bar{\delta}: \vec{E} \rightarrow \mathbb{Q}$ which sums to 0 around any cycle of $\vec{G}$ that lifts to a cycle of $G$, (ii) exporting $\bar{\delta}$ via the action of $\mathcal{H}$ to a function $\delta$ on the directed edges of $G$, and (iii) summing $\delta$ to obtain a height function $h$.

We may assume that $\mathcal{B} \neq \varnothing$, since otherwise $G$ is a tree and the claim is trivial. Let $\overrightarrow{\mathcal{B}}$ be the projections onto $\vec{G}$ of the $2|\mathcal{B}|$ oriented cycles derived from $\mathcal{B}$. The set $\overrightarrow{\mathcal{B}}$ generates a directed cycle space $\overrightarrow{\mathcal{C}}(\overrightarrow{\mathcal{B}})$ over $\mathbb{Q}$, which is a subspace of the directed cycle space $\overrightarrow{\mathcal{C}}(\vec{G})$ of $\vec{G}$ (also over $\mathbb{Q}$ ). See $[14,27,29]$ for accounts of the undirected and directed vector spaces associated with the cycles of a graph.

## Lemma 6.1.

(a) The dimensions $\rho:=\operatorname{dim}(\overrightarrow{\mathcal{C}}(\overrightarrow{\mathcal{B}}))$ and $\Delta:=\operatorname{dim}(\overrightarrow{\mathcal{C}}(\vec{G}))$ satisfy $\rho<\Delta$.
(b) The cycle space $\overrightarrow{\mathcal{C}}(\vec{G})$ has a basis $\left\{C_{1}, \ldots, C_{\rho}, C_{\rho+1}, \ldots, C_{\Delta}\right\}$ of oriented cycles such that $\left\{C_{1}, C_{2}, \ldots, C_{\rho}\right\}$ is a basis of the subspace $\overrightarrow{\mathcal{C}}(\overrightarrow{\mathcal{B}})$.

Proof. (a) First, a reminder. Let $H=(W, F)$ be an undirected graph, and let $T$ be a spanning forest of $H$. The set of cycles formed by adding one further edge to $T$ forms a basis for the cycle space $\mathcal{C}(H)$, denoted $B(H, T)$. In particular, the dimension of the space is the number of edges not belonging to $T$, so that $\operatorname{dim}(\mathcal{C}(H))=|F|-|T|$ where $K$ is the number of components of $H$.

Let $\overline{\mathcal{B}}$ be the set of projections of $\mathcal{B}$ onto $\bar{G}$, and let $\bar{E}^{\prime}(\subseteq \bar{E})$ be the union of the edges of $\overline{\mathcal{B}}$. Let $T^{\prime}$ (respectively, $T$ ) be a spanning forest of $\bar{G}^{\prime}:=\left(\bar{V}, \bar{E}^{\prime}\right)$ (respectively, $\bar{G})$ such that $T^{\prime}$ is a subgraph of $T$. The cycle space $\mathcal{C}(\bar{G})$ has dimension $\Delta^{\prime}:=$ $|\bar{E}|-|T|$, and $\mathcal{C}(\overline{\mathcal{B}})$ has dimension $\rho^{\prime}:=\left|\bar{E}^{\prime}\right|-\left|T^{\prime}\right|$. Note that $B\left(\bar{G}^{\prime}, T^{\prime}\right) \subseteq B(\bar{G}, T)$.

Since each $\bar{\beta} \in \overline{\mathcal{B}}$ is, by assumption, a cycle, and is in addition the projection of a cycle, every lift of $\bar{\beta}$ is a cycle of $G$. Therefore, for $\bar{\sigma} \in \mathcal{C}(\overline{\mathcal{B}})$, every lift of $\bar{\sigma}$ lies in $\mathcal{C}(G)$. Let $l_{1}$ be a shortest path of $G$ from $\mathbf{1}$ to $V \backslash\{\mathbf{1}\}$. The projection $\bar{l}_{1}$ is a cycle of $\bar{G}$ with at least one lift that is a SAW of $G$. Therefore, $\bar{l}_{\mathbf{1}} \in \mathcal{C}(\bar{G}) \backslash \mathcal{C}(\overline{\mathcal{B}})$, and hence $\rho^{\prime}<\Delta^{\prime}$.

The graph $\vec{G}$ has the property that $\vec{e} \in \vec{E}$ if and only if $-\vec{e} \in \vec{E}$. Therefore, its directed cycle space $\overrightarrow{\mathcal{C}}(\vec{G})$ has a basis of oriented cycles comprising the set $\{(\vec{e},-\vec{e})$ : $e \in \bar{E}\}$ together with appropriately directed lifts of $B(\bar{G}, T)$. See [14, Thm 14]. Hence, $\Delta:=\operatorname{dim}(\overrightarrow{\mathcal{C}}(\vec{G}))$ satisfies $\Delta=|\bar{E}|+\Delta^{\prime}$.

Similarly, the directed cycle space $\overrightarrow{\mathcal{C}}(\overrightarrow{\mathcal{B}})$ has a basis of oriented cycles comprising the set $\left\{(\vec{e},-\vec{e}): e \in \bar{E}^{\prime}\right\}$ together with appropriately directed lifts of $B\left(\bar{G}^{\prime}, T^{\prime}\right)$. Hence, $\rho:=\operatorname{dim}(\overrightarrow{\mathcal{C}}(\overrightarrow{\mathcal{B}}))$ satisfies $\rho=\left|\bar{E}^{\prime}\right|+\rho^{\prime}<\Delta$. Furthermore, the latter basis is a subset of the given basis of $\overrightarrow{\mathcal{C}}(\vec{G})$.

Let $\bar{\delta}: \bar{E} \rightarrow \mathbb{Q}$, and extend the domain of $\bar{\delta}$ to $\vec{E}$ in the following manner. To each $e \in \bar{E}$, we assign an arbitrary orientation. For $\vec{e} \in \vec{E}$, we set

$$
\bar{\delta}(\vec{e}):= \begin{cases}\bar{\delta}(e) & \text { if } e \text { is oriented in the direction } \vec{e}, \\ -\bar{\delta}(e) & \text { otherwise }\end{cases}
$$

We shall require $\bar{\delta}$ to have certain properties as follows. Consider the following system of linear equations in the values $\bar{\delta}(e), e \in \bar{E}$ :

$$
\begin{align*}
& \sum_{\vec{e} \in C_{i}} \bar{\delta}(\vec{e})=0, \quad 1 \leq i \leq \Delta-1  \tag{6.1}\\
& \sum_{\vec{e} \in C_{\Delta}} \bar{\delta}(\vec{e})=1 \tag{6.2}
\end{align*}
$$

This system possesses a solution, since both coefficient matrix and augmented matrix have rank $\Delta$. Furthermore, there is a rational solution, since the equations
have integral coefficients. Let $\bar{\delta}$ be such a solution, and, for a directed $\vec{f}$ derived from an edge $f \in E$, let $\delta(\vec{f})=\delta(\vec{e})$ where $\vec{f} \in E$ projects onto $\vec{e} \in \vec{E}$.

Since $\mathcal{C}(G)$ is generated by $\mathcal{B}$, and $\overrightarrow{\mathcal{C}}(\overrightarrow{\mathcal{B}})$ is spanned by $C_{1}, C_{2}, \ldots, C_{\rho}$, a directed closed walk $W$ on $G$ may be expressed in the form

$$
W=\sum_{i=1}^{\rho} \lambda_{i}\left[\gamma_{i} C_{i}\right]
$$

for $\lambda_{i} \in \mathbb{Z}$ and $\gamma_{i} \in \mathcal{H}$. By (6.1) and the $\mathcal{H}$-invariance of $\delta$,

$$
\begin{equation*}
\sum_{\vec{e} \in W} \delta(\vec{e})=0 \tag{6.3}
\end{equation*}
$$

Let $h^{\prime}: V \rightarrow \mathbb{Q}$ be given as follows. Let $h^{\prime}(\mathbf{1})=0$. For $v \in V$, find a directed path $l_{v}$ from 1 and $v$, and define

$$
\begin{equation*}
h^{\prime}(v)=\sum_{\vec{e} \in l_{v}} \delta(\vec{e}) . \tag{6.4}
\end{equation*}
$$

By (6.3), $h^{\prime}$ is well defined in the sense that $h^{\prime}(v)$ is independent of the choice of $l_{v}$.
The function $h^{\prime}$ takes rational values. Since $\delta$ is $\mathcal{H}$-invariant, there exists $m \in \mathbb{N}$ such that $h:=m h^{\prime}$ takes integer values. The resulting $h$ may fail to be a graph height function only in that it may not satisfy condition (c) of Definition 3.1. We shall explain in the following construction how to find a solution $\bar{\delta}$ such that (c) holds.

We show next how such a solution $\bar{\delta}$ of (6.1)-(6.2) may be found via an explicit iterative construction, illustrated in Example 6.3. The values $\bar{\delta}(e)$ will be revealed one by one. At each stage, edges $\vec{e},-\vec{e}$ (or, equivalently, the edge $e \in \bar{E}$ ) are said to be explored if $\bar{\delta}(e)$ is known. The set of explored edges will increase as the stages progress, until it becomes the entire edge-set of $\vec{G}$.

The cycle $C_{\Delta}$ plays a special role, and we abbreviate it to $C$. Let $\bar{c}$ be a vertex of $C$. Since $\mathcal{H}$ is a normal subgroup of $\Gamma$, and $\Gamma$ acts transitively on $G, \Gamma$ acts transitively on $\vec{G}$ as well. For $\bar{v} \in \bar{V}$, there exists $\gamma \in \Gamma$ such that $\gamma(\bar{c})=\bar{v}$. Let $C(\bar{v})=\gamma C$, so that $C(\bar{v})$ is a directed cycle of $\vec{G}$ through $\bar{v}$.

Let $U$ be the union of the edge-sets of the $\{C(\bar{v}): \bar{v} \in \bar{V}\}$ viewed as undirected cycles, and let $S_{1}, S_{2}, \ldots, S_{k}$ be the vertex-sets of the connected components of $(\bar{V}, U)$. Since $U$ touches every member of $\bar{V}$, for each $i$ there exists $j \neq i$ and $\vec{e}=\left[v_{i}, v_{j}\right\rangle \in \vec{E}$ such that $\bar{v}_{i} \in S_{i}, \bar{v}_{j} \in S_{j}$. Starting from $S_{1}$, we find an edge $\vec{e}_{1} \notin U$ that connects $S_{1}$ and some $S_{i_{1}}$ with $i_{1} \neq 1$, then an edge $\vec{e}_{2} \notin U$ that connects $S_{1} \cup S_{i_{1}}$ and some $S_{i_{2}}$, and so on. This results in a set $F=\left\{\vec{e}_{1}, \vec{e}_{2}, \ldots, \vec{e}_{k-1}\right\}$ such that $(\bar{V}, U \cup F)$ is connected.

Let $S_{1}$ comprise the cycles $C\left(\bar{v}_{i}\right)$ for $1 \leq i \leq d$. We may assume without loss of generality that $v_{1}=\bar{c}$ and, for $2 \leq i \leq d, C\left(\bar{v}_{i}\right)$ and $\bigcup_{1 \leq j<i} C\left(\bar{v}_{j}\right)$ have at least one vertex in common. We explain next how to define $\bar{\delta}$ on the edges of $S_{1}$.
Stage 1. We consider first the edges in $C$. For each directed edge $\vec{e} \in C$, we set $\delta(\vec{e})=-\delta(-\vec{e})=1 /|C|$.

Stage 2. We describe how the domain of $\bar{\delta}$ may be extended in stages. At each stage, we shall consider a path of unexplored edges, and assign $\bar{\delta}$-values according to a given set of rules. The argument proceeds by an induction of which the hypothesis is as follows.

For any set $H$ of currently explored edges, let

$$
\Sigma(H)=\sum_{\vec{e} \in H} \bar{\delta}(\vec{e}) .
$$

Hypothesis 6.2. Let $F$ be the set of currently explored edges of $\vec{G}$, and let $W$ be the set of their endpoints.
(a) For every distinct pair $\bar{a}, \bar{b} \in W$, there exists a directed $S A W R$ of $(\vec{G}, F)$ from $\bar{a}$ to $\bar{b}$ such that $\Sigma(R) \notin \mathbb{N}$.
(b) For any directed, closed walk $W$ of $\vec{G}$ using edges in $F$,

$$
\begin{equation*}
\Sigma(W)=\lambda_{\Delta}, \tag{6.5}
\end{equation*}
$$

where $W=\sum_{i=1}^{\Delta} \lambda_{i} C_{i}$, with $\lambda_{i} \in \mathbb{Z}$, is the unique representation of $W$ in terms of the basis of $\overrightarrow{\mathcal{C}}(\vec{G})$.

Note that the hypothesis is valid at the end of Stage 1, at which point we may write $F=\{e \in \bar{E}: \vec{e} \in C\}$ for the updated set of explored edges. Next consider $C\left(\bar{v}_{2}\right)$, which, by construction, intersects $C$. The cycle $C\left(\bar{v}_{2}\right)$ is cut by $C$ into edge-disjoint segments, endpoints of which lie in $C$. Let $(\bar{a} \leftrightarrow \bar{b})$ denote an undirected sub-path of $C\left(\bar{v}_{2}\right)$ containing one or more edges, and with endvertices $\bar{a}, \bar{b} \in C$ such that no vertex other than these endvertices lies in $C$. Let $\pi=(\bar{a} \rightarrow \bar{b})$ denote a directed segment along $C\left(\bar{v}_{2}\right)$ such that there are no vertices of $C$ between $\bar{a}$ and $\bar{b}$. There are two cases depending on whether or not $\bar{a}=\bar{b}$.
Case I. Suppose first that $\bar{a} \neq \bar{b}$. By the induction hypothesis, we may find a subset $R$ of $F$ that forms a directed SAW from $\bar{b}$ and $\bar{a}$ and satisfies

$$
\begin{equation*}
\Sigma(R) \notin \mathbb{N} \tag{6.6}
\end{equation*}
$$

Then $R$, combined with $\pi$, forms a directed closed walk of $\vec{G}$, denoted by $W^{\prime}$. By Lemma 6.1(b), $W^{\prime}$ has a unique representation in the form

$$
\begin{equation*}
W^{\prime}=\sum_{i=1}^{\Delta} \lambda_{i} C_{i}, \tag{6.7}
\end{equation*}
$$

with $\lambda_{i} \in \mathbb{Z}$. We assign $\bar{\delta}$-values to the edges of $\pi$ in such a way that $\Sigma\left(W^{\prime}\right)=\lambda_{\Delta}$, that is, such that

$$
\Sigma(\pi)=\Sigma\left(W^{\prime}\right)-\Sigma(R)=\lambda_{\Delta}-\Sigma(R) \neq 0
$$

by (6.6).
Having determined the sum $\Sigma(\pi)$, we distribute it between the members of $\pi$ in such a way that the $\bar{\delta}(\vec{e}), \vec{e} \in \pi$, are non-zero and have the same sign. There is an additional condition, as follows. Let $F^{\prime}$ be the updated set of explored edges, and $W^{\prime}$ their endvertices. We require that, for any distinct pair $\bar{a}, \bar{b} \in W^{\prime}$, there exists a directed SAW of $F^{\prime}$ from $\bar{a}$ to $\bar{b}$ with $\Sigma(R) \notin \mathbb{N}$. This may be achieved by small variations in an equidistribution of $\Sigma(\pi)$ around $\pi$.

It may be checked (see the general induction step below) that Hypothesis 6.2(b) remains true after completion of the above stage.
Case II. Assume now that $\bar{a}=\bar{b}$. This can happen only if $\bar{a}$ is the unique common vertex of $C$ and $C\left(\bar{v}_{2}\right)$. In this case, we set $\Sigma\left(C\left(\bar{v}_{2}\right)\right)=1$, and we distribute this sum between the edges of $C\left(\bar{v}_{2}\right)$ in such a way that the values are non-zero with the same sign, and furthermore Hypothesis 6.2(a) is preserved.

We iterate the above process, at each stage exploring another segment of $C\left(v_{2}\right)$, until no such segment remains.

The general induction step is as follows. Assume Hypothesis 6.2 is valid so far, and we are required to assign $\bar{\delta}$-values to the edges belonging to a (currently unexplored) directed SAW $\pi=(\bar{a} \rightarrow \bar{b})$ satisfying the condition that $\bar{a}$ and $\bar{b}$ are incident to one or more currently explored edges, but no other vertex of $\pi$ has this property.
Case $I^{\prime}$. Assume first that $\bar{a} \neq \bar{b}$. Let $R$ be an explored SAW on $\vec{G}$ which is directed from $\bar{b}$ to $\bar{a}$ and satisfies $\Sigma(R) \notin \mathbb{N}$. Then $R$, combined with $\pi$, forms a directed closed walk $W^{\prime}$, which has a unique representation in the form (6.7) with $\lambda_{i} \in \mathbb{Z}$. We assign values to the $\bar{\delta}(\vec{e}), \vec{e} \in \pi$, in the same manner as above, such that they are non-zero with the same sign, and such that Hypothesis $6.2(\mathrm{a})$ is preserved.

We show next that Hypothesis $6.2(\mathrm{~b})$ remains true after this has been done. Let $W$ be some explored, directed, closed walk. If $W$ uses no edge of $\pi:=(\bar{a} \rightarrow \bar{b})$ in either direction, then (6.5) holds as before. Assume $W$ uses one or more edges of $\pi$ in one or the other direction. Since no internal vertex of $\pi$ is incident to a previously explored edge, $W$ uses every edge of $\pi$ an equal number of times (say $f$
times) forwards, and similarly an equal number of times (say $b$ times) backwards. Let $q=f-b$.

Let $W^{\prime \prime}$ be the walk that follows $W$ but subject to the difference that, whenever $W$ wishes to traverse $\pi$ forwards (respectively, backwards) it is redirected along $R$ backwards (respectively, forwards). Then $W^{\prime \prime}$ is a closed walk of previously explored edges which uses no edges of $\pi$. By the hypothesis, $\Sigma\left(W^{\prime \prime}\right)=0$, so that

$$
\Sigma(W)=\Sigma\left(W^{\prime \prime}\right)+q \Sigma\left(W^{\prime}\right)=0
$$

as required. It follows that the values assigned to $\vec{e}, \vec{e} \in \pi$, do not depend on the choice of $R$, and furthermore that (6.5) holds for all currently explored walks.
Case II'. When $\bar{a}=\bar{b}$, we proceed as in Case II above.
Stage 3. Having assigned $\bar{\delta}$-values to edges in $C$ and $C\left(\bar{v}_{2}\right)$, we continue by induction to the remaining cycles in $S_{1}$.
Stage 4. We set $\bar{\delta}\left(\vec{e}_{1}\right)=0$, and we consider the exploration of $S_{2}$, beginning with $C(\bar{v})$ where $\bar{v}$ is the endpoint of $e_{1}$ lying in $S_{2}$. We now assign $\bar{\delta}$-values to the edges of $C(\bar{v})$ by the recipe of Stage 2 above. The cycles $C\left(\bar{v}_{k}\right)$ of $S_{2}$ are then explored in sequence, following the previous process. There is no interaction at this stage between edges of $S_{1}$ and those of $S_{2}$. When $S_{2}$ is complete, we declare $\delta\left(\vec{e}_{2}\right)=0$ and continue with $S_{3}$, and so on.
Stage 5. Once Stage 4 is complete, every vertex of $\vec{G}$ is incident to some explored edge. There may however remain unexplored edges, and any such $\vec{e}=[\bar{a}, \bar{b}\rangle \in \vec{E}$ is allocated a $\bar{\delta}$-value by the recipe of Stage 2 . Let $R$ be an explored SAW from $\bar{b}$ to $\bar{a}$, and let $W^{\prime}$ be the walk obtained by combining $\vec{e}$ with $R$. We set $\bar{\delta}(\vec{e})=\Sigma\left(W^{\prime}\right)-\Sigma(R)$, where $\Sigma\left(W^{\prime}\right)$ satisfies (6.5). It may happen that $\bar{\delta}(\vec{e})=0$, and it may be checked as above that Hypothesis $6.2(\mathrm{~b})$ is preserved (condition (a) is unimportant at this stage).

The construction of $\bar{\delta}$ is complete. A final note. By inspection of the construction, for $\bar{v} \in \bar{V}$, there exist $\bar{u}, \bar{w} \in \partial \bar{v}$ such that $\bar{\delta}([\bar{u}, \bar{v}\rangle), \bar{\delta}([\bar{v}, \bar{w}\rangle)>0$. Therefore, the ensuing $h^{\prime}$ of (6.4) satisfies Definition 3.1(c).
Example 6.3. The above proof is illustrated by a simple example. Take $G=\mathbb{Z}^{2}$, let $\Gamma$ be the group of translations, and let $\mathcal{H} \leq \Gamma$ be the subgroup of translations generated by the horizontal and vertical shift by three units. The undirected quotient graph $\bar{G}$ has vertex-set $\{0,1,2\}^{2}$ with toroidal edges, as in Figure 6.1. We take each $C(\bar{v})$ to be the upwards oriented 3 -cycle through $\bar{v}$.

## 7. Proof of Theorem 4.2

We adapt and extend the 'bridge decomposition' approach of Hammersley and Welsh [25], which was originally specific to the hypercubic lattice. A partition $\Pi$ of


Figure 6.1. An illustration of the construction of the function $3 \bar{\delta}$ on the quotient graph $\vec{G}$ of Example 6.3. Directions and magnitudes are assigned to the edges in an iterative manner, in such a way that the sum of the values around any cycle that lifts to a cycle of $G$ is 0 . In the leftmost figure, the values have been determined on the cycles $C(\overline{\mathbf{1}})$ and $C(1,0)$, where $\overline{\mathbf{1}}=(0,0)$. In the central figure, the values on $C(2,1)$ have been added, and the missing values are provided in the rightmost figure.
the integer $n \geq 1$ into distinct integers is an expression of the form $n=a_{1}+a_{2}+\cdots+a_{k}$ with integers $a_{i}$ satisfying $a_{1}>a_{2}>\cdots>a_{k}>0$ and some $k=k(\Pi) \geq 1$. The number $k(\Pi)$ is the order of the partition $\Pi$, and the number of partitions of $n$ is denoted $P(n)$. We recall two facts about such partitions.

Lemma 7.1. The order $k=k(\Pi)$ and the number $P(n)$ satisfy

$$
\begin{array}{ll}
k(k+1) \leq 2 n & \text { for all partitions } \Pi \text { of } n, \\
\log P(n) \sim \pi \sqrt{n / 3} & \text { as } n \rightarrow \infty . \tag{7.2}
\end{array}
$$

Proof. The sum of the first $r$ natural numbers is $\frac{1}{2} r(r+1)$. Therefore, if $r$ satisfies $\frac{1}{2} r(r+1)>n$, the order of $\Pi$ is at most $r-1$. See [26] for a proof of (7.2).

Let $G$ be a graph with the given properties, and let $(h, \mathcal{H})$ be a graph height function on $G$. For the given $(h, \mathcal{H})$, and $v \in V$, we let $b_{n}(v)$ and $c_{n}=c_{n}(\mathbf{1})$ be the counts of bridges and half-space SAWs starting at $v$ and $\mathbf{1}$, respectively, as in Section 4. Recall the constants $d=d(h), r=r(h, \mathcal{H})$ given after Definition 3.1.

Proposition 7.2. There exists $A=A(r)$ such that $c_{n} \leq d n e^{A \sqrt{n}} \beta^{n}$.
Proof. Let $n \geq 1$, and let $\pi=\left(\pi_{0}, \pi_{1}, \ldots, \pi_{n}\right)$ be an $n$-step half-space SAW starting at $\pi_{0}=1$. Let $n_{0}=0$, and for $j \geq 1$, define $S_{j}=S_{j}(\pi)$ and $n_{j}=n_{j}(\pi)$ recursively
as follows:

$$
S_{j}=\max _{n_{j-1} \leq m \leq n}(-1)^{j}\left[h\left(\pi_{n_{j-1}}\right)-h\left(\pi_{m}\right)\right],
$$

and $n_{j}$ is the largest value of $m$ at which the maximum is attained. The recursion is stopped at the smallest integer $k=k(\pi)$ such that $n_{k}=n$, so that $S_{k+1}$ and $n_{k+1}$ are undefined. Note that $S_{1}$ is the span of $\pi$ and, more generally, $S_{j+1}$ is the span of the SAW $\bar{\pi}^{j+1}:=\left(\pi_{n_{j}}, \pi_{n_{j}+1}, \ldots, \pi_{n_{j+1}}\right)$. Moreover, each of the subwalks $\bar{\pi}^{j+1}$ is either a bridge or a reversed bridge. We observe that $S_{1}>S_{2}>\cdots>S_{k}>0$.

For a decreasing sequence of $k \geq 2$ positive integers $a_{1}>a_{2}>\cdots>a_{k}>0$, let $B_{n}\left(a_{1}, a_{2}, \ldots, a_{k}\right)$ be the set of ( $n$-step) half-space walks from 1 such that $k(\pi)=k$, $S_{1}(\pi)=a_{1}, \ldots, S_{k}(\pi)=a_{k}$ and $n_{k}(\pi)=n$ (and hence $S_{k+1}$ is undefined). In particular, $B_{n}(a)$ is the set of $n$-step bridges from 1 with span $a$.

Let $\pi \in B_{n}\left(a_{1}, a_{2}, \ldots, a_{k}\right)$. We describe next how to perform surgery on $\pi$ in order to obtain a SAW $\pi^{\prime}$ satisfying

$$
\pi^{\prime} \in \begin{cases}B_{n+\sigma}\left(a_{1}+a_{2}+a_{3}+\delta, a_{4}, \ldots, a_{k}\right) & \text { if } k \geq 3  \tag{7.3}\\ B_{n+\sigma}\left(a_{1}+a_{2}+\delta\right) & \text { if } k=2\end{cases}
$$

for some $\sigma=\sigma(\pi)$ and $\delta=\delta(\pi)$ satisfying $0 \leq \sigma \leq 2 r$ and $\delta \geq 0$. The argument is different from that of the corresponding step of [25] since $G$ may not be invariant under reflections, and the conclusion (7.3) differs from that of [25] through the inclusion of the terms $\sigma, \delta$. The proof of (7.3) is easier when $\mathcal{H}$ acts transitively, and thus we assume that $\mathcal{H}$ acts quasi-transitively but not transitively.

The new SAW $\pi^{\prime}$ is constructed in the following way, as illustrated in Figure 7.1. Suppose first that $k \geq 3$.

1. Let $\pi_{1}^{\prime}$ be the sub-SAW $\bar{\pi}^{1}$ from $\pi_{0}=\mathbf{1}$ to the vertex $\pi_{n_{1}}$.
2. Let $m=\min \left\{N>n_{1}: h\left(\pi_{N}\right)=S_{1}-S_{2}\right\}$, and let $\nu_{1}:=\left(\pi_{n_{1}}, \ldots, \pi_{m}\right)$ and $\nu_{2}=\left(\pi_{m}, \ldots, \pi_{n}\right)$ be the two sub-SAWs of $\pi$ with the given endvertices.
(a) If $\pi_{m} \notin \mathcal{H} \pi_{n_{1}}$, we find $\alpha \in \mathcal{H}$ such that: (i) $a_{1}<h\left(\alpha \pi_{m}\right)$ and (ii) there is a SAW $\nu\left(\pi_{n_{1}}, \alpha \pi_{m}\right)$ with the given endvertices, of length not exceeding $r$, and of which every vertex $x$, other than its endvertices, satisfies $a_{1}<h(x)<h\left(\alpha \pi_{m}\right)$.
(b) If $\pi_{m} \in \mathcal{H} \pi_{n_{1}}$, we find $\alpha \in \mathcal{H}$ such that $\alpha \pi_{m}=\pi_{n_{1}}$, and write $\nu\left(\pi_{n_{1}}, \alpha \pi_{m}\right)$ for the 0 -step SAW at $\pi_{n_{1}}$.
The union of the three (undirected) SAWs $\pi_{1}^{\prime}, \nu\left(\pi_{n_{1}}, \alpha \pi_{m}\right)$, and $\alpha \nu_{1}$ is a SAW, denoted $\pi_{2}^{\prime}$, from 1 to $\alpha \pi_{n_{1}}$. In concluding that $\pi_{2}^{\prime}$ is a SAW, we have made use of Definition 3.1(b). Note that $a_{1}+a_{2} \leq h\left(\alpha \pi_{n_{1}}\right)$.
3. As in Step 2, we next find $\alpha^{\prime} \in \mathcal{H}$ such that $h\left(\alpha \pi_{n_{1}}\right) \leq h\left(\alpha^{\prime} \pi_{m}\right)$ and a SAW $\nu\left(\alpha \pi_{n_{1}}, \alpha^{\prime} \pi_{m}\right)$ with the given endvertices and the previous type. The union of the three (undirected) SAWs $\pi_{2}^{\prime}, \nu\left(\alpha \pi_{n_{1}}, \alpha^{\prime} \pi_{m}\right)$, and $\alpha^{\prime} \nu_{2}$, is a SAW, denoted $\pi_{3}^{\prime}$, from 1 to $\alpha^{\prime} \pi_{n}$.


Figure 7.1. The solid SAW lies in $B_{n}\left(a_{1}, a_{2}, a_{3}\right)$. We translate the blue path connecting $\pi_{n_{1}}$ to $\pi_{m}$, and also the third sub-SAW of $\pi$, thereby obtaining a SAW in $B_{n+\sigma}\left(a_{1}+a_{2}+a_{3}+\delta\right)$. After translation, the paths are dashed.

We note the repeated use of Proposition 3.2, and also Definition 3.1(b). It follows that $\pi^{\prime} \in B_{n+\sigma}\left(a_{1}+a_{2}+a_{3}+\delta, a_{4}, \ldots, a_{k}\right)$ for some $0 \leq \sigma \leq 2 r$ and $\delta \geq 0$. The mapping $\pi \mapsto \pi^{\prime}$ is not one-to-one since $\pi$ may not be reconstructable from knowledge of $\pi^{\prime}$ without identification of the intermediate $\operatorname{SAWs} \nu(\cdot)$ in steps 2 and 3. However, since the intermediate SAWs have length no greater than $r$, the mapping is at most $r^{2}$-to-one.

Suppose now that $k=2$. At step 2 above, we have that $h\left(\pi_{n}\right)=S_{1}-S_{2}$, so that $\pi^{\prime} \in B_{n+\sigma}\left(a_{1}+a_{2}+\delta\right)$ for some $0 \leq \sigma \leq r$ and $\delta \geq 0$. As above, the map $\pi \mapsto \pi^{\prime}$ is at most $r$-to-one.

Let $T=a_{1}+a_{2}+\cdots+a_{k}$, and write $\sum_{a}^{(k, T)}$ for the summation over all finite integer sequences $a_{1}>\cdots>a_{k}>0$ with given length $k$ and sum $T$. By iteration of (7.3),

$$
\begin{aligned}
c_{n} & \leq \sum_{T=1}^{d n} \sum_{k=1}^{n} \sum_{a}{ }^{(k, T)}\left|B_{n}\left(a_{1}, \ldots, a_{k}\right)\right| \\
& \leq \sum_{T=1}^{d n} \sum_{k=1}^{n} \sum_{a}^{(k, T)} r^{k}\left|B_{n+s}(T+\Delta)\right|,
\end{aligned}
$$

for some $0 \leq s \leq k r$ and $\Delta \geq 0$. By (7.1)-(7.2), and (4.7), there exists a constant $A=A(r)$ such that

$$
\begin{aligned}
c_{n} & \leq \sum_{T=1}^{d n} \sum_{k=1}^{n} \sum_{a}{ }^{(k, T)} r^{k} \beta^{n+k r+r} \\
& \leq \sum_{T=1}^{d n} \sum_{k=1}^{n} \sum_{a}{ }^{(k, T)} \beta^{n+r}\left(\beta^{r} r\right)^{\sqrt{2 n}} \leq d n e^{A \sqrt{n}} \beta^{n}
\end{aligned}
$$

as required.
Proposition 7.3. There exists $B=B(d, r)>0$ such that

$$
\sigma_{n} \leq B n^{3} e^{B \sqrt{n}} \beta^{n}, \quad n \geq 1
$$

Proof. Let $\pi=\left(\pi_{0}, \pi_{1}, \ldots, \pi_{n}\right) \in \Sigma_{n}$. Let $\mu=\min _{0 \leq i \leq n} h\left(\pi_{i}\right)$ and $m=\max \{i$ : $\left.h\left(\pi_{i}\right)=\mu\right\}$. We construct two half-space SAWs as follows.

Find $\mathbf{1}^{\prime} \in \mathcal{H} \mathbf{1}$ such that, by Proposition 3.2, there exists a SAW $\nu\left(\mathbf{1}^{\prime}, \pi_{m}\right)$ with the given endvertices, of length not exceeding $r$, and of which every vertex $x$, other than its endvertices, satisfies $h\left(\mathbf{1}^{\prime}\right)<h(x)<h\left(\pi_{m}\right)$. If $\pi_{m} \in \mathcal{H} \mathbf{1}$, we take $\mathbf{1}^{\prime}=\pi_{m}$ and $\nu\left(\mathbf{1}^{\prime}, \pi_{m}\right)$ the 0 -step SAW at $\pi_{m}$. The union of the two SAWs $\nu\left(\mathbf{1}^{\prime}, \pi_{m}\right)$ and $\left(\pi_{0}, \ldots, \pi_{m}\right)$ contains a half-space SAW from $\mathbf{1}^{\prime}$ with length $m+\sigma$ for some $0 \leq \sigma \leq r$. Similarly, the union of $\nu\left(\mathbf{1}^{\prime}, \pi_{m}\right)$ and $\left(\pi_{m}, \ldots, \pi_{n}\right)$ contains a half-space SAW from $\mathbf{1}^{\prime}$ with length $n-m+\sigma$.

By Proposition 7.2,

$$
\sigma_{n} \leq \sum_{m=0}^{n} U_{m+r} U_{n-m+r}
$$

where $U_{s}=d s e^{A \sqrt{s}} \beta^{s}$. Therefore,

$$
\begin{aligned}
\sigma_{n} & \leq d^{2} \beta^{n+2 r} \sum_{m=0}^{n}(m+r)(n-m+r) \exp (A \sqrt{m+r}+A \sqrt{n-m+r}) \\
& \leq d^{2} \beta^{n+2 r} n(n+2 r)^{2} e^{A \sqrt{2(n+2 r)}}
\end{aligned}
$$

by the inequality $\sqrt{x}+\sqrt{y} \leq \sqrt{2 x+2 y}$. The claim follows.
It is trivial that $b_{n} \leq \sigma_{n}$, whence $\beta \leq \mu$. The reverse inequality follows by Proposition 7.3, and the theorem is proved.

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