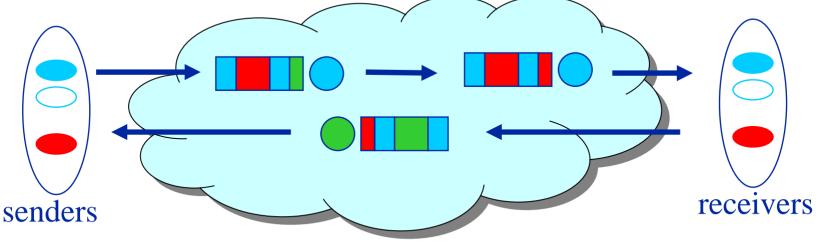
Models of network routing and congestion control

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www.statslab.cam.ac.uk/~frank/TALKS/amherst.html

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End-to-end congestion control



Senders learn (through feedback from receivers) of congestion at queue, and slow down or speed up accordingly. With current TCP, throughput of a flow is proportional to

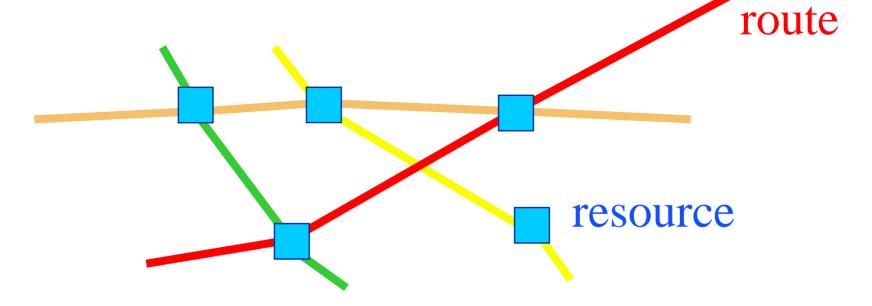
T = round-trip time, p = packet drop probability. (Jacobson 1988, Mathis, Semke, Mahdavi, Ott 1997, Padhye, Firoiu, Towsley, Kurose 1998, Floyd & Fall 1999)

Model definition

- We want to describe a network model, with fluctuating numbers of flows
- We first need
 - notation for network structure
 - abstraction of rate allocation
- Then we need to define the random nature of flow arrivals and departures

Network structure (J, R, A)

- set of resources J
- *R* set of routes
- $A_{jr} = 1$ if resource *j* is on route *r* $A_{jr} = 0$ otherwise



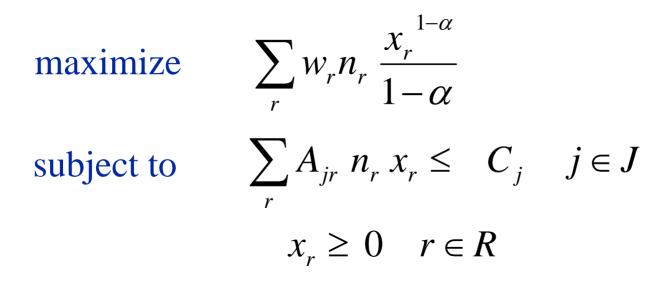
Rate allocation

- w_r weight of route r
- n_r number of flows on route r
- x_r rate of each flow on route r

Given the vector $n = (n_r, r \in R)$ how are the rates $x = (x_r, r \in R)$ chosen ?

Optimization formulation

Suppose x = x(n) is chosen to



(weighted α -fair allocations, Mo and Walrand 2000)

$$0 < \alpha < \infty$$
 (replace $\frac{x_r^{1-\alpha}}{1-\alpha}$ by $\log(x_r)$ if $\alpha = 1$)

Solution $x_{r} = \left(\frac{W_{r}}{\sum_{j} A_{jr} p_{j}(n)}\right)^{1/\alpha} \qquad r \in R$

 $p_j(n)$ - shadow price (Lagrange multiplier) for the resource *j* capacity constraint

Observe alignment with square-root formula when

$$\alpha = 2$$
, $w_r = 1/T_r^2$, $p_r \approx \sum_j A_{jr} p_j$

Examples of α -fair allocations

maximize
$$\sum_{r} w_{r} n_{r} \frac{x_{r}^{1-\alpha}}{1-\alpha}$$

subject to
$$\sum_{r} A_{jr} n_{r} x_{r} \leq C_{j} \quad j \in J$$
$$x_{r} \geq 0 \quad r \in R$$

$$x_r = \left(\frac{W_r}{\sum_j A_{jr} p_j(n)}\right)^{1/\alpha} r \in R$$

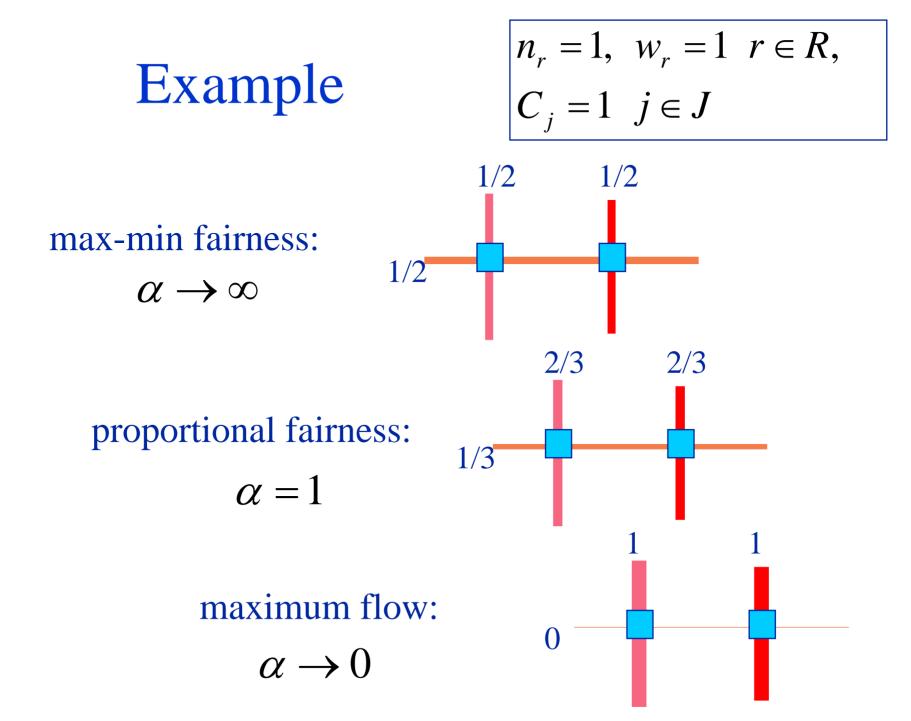
$$\alpha \to 0 \quad (w = 1)$$

$$\alpha \to 1 \quad (w = 1)$$

$$\alpha = 2 \quad (w_r = 1/T_r^2)$$

$$\alpha \to \infty \quad (w = 1)$$

- maximum flow
- proportionally fair
- TCP fair
- max-min fair

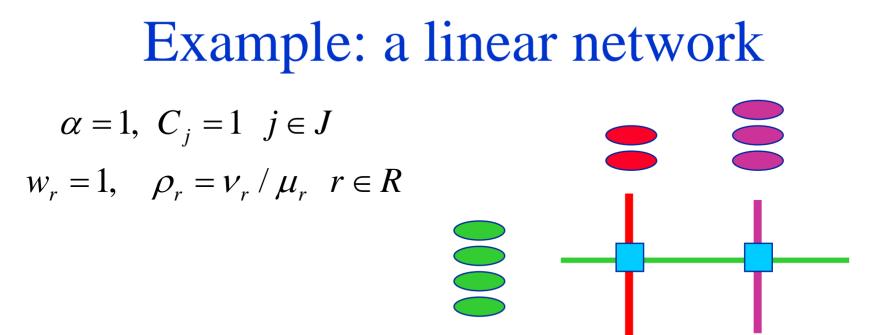


Flow level model

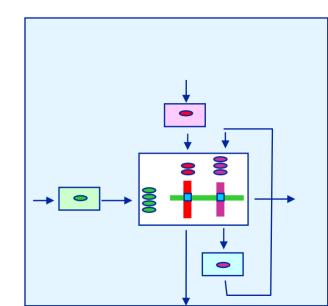
Define a Markov chain $n(t) = (n_r(t), r \in R)$ with transition rates

- $n_r \rightarrow n_r + 1$ at rate v_r $r \in R$ $n_r \rightarrow n_r - 1$ at rate $n_r x_r(n) \mu_r$ $r \in R$
- Poisson arrivals, exponentially distributed file sizes
- model originally due to Roberts and Massoulié 1998

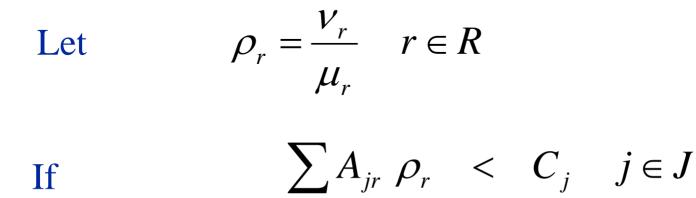
for a single resource (or a linear network with proportional fairness) we can allow arbitrary file size distributions – becomes a quasi-reversible node



Quasi-reversible, with: $\pi(n_0, n_1, n_2) = B \begin{pmatrix} \sum_{i=0}^{2} n_i \\ n_0 \end{pmatrix} \prod_{i=0}^{2} \rho_i^{n_i}$ $B = (1 - \rho_0)^{-1} \prod_{i=1}^{2} (1 - \rho_0 - \rho_i)$



Stability



and resource allocation is weighted α -fair then the Markov chain $n(t) = (n_r(t), r \in R)$ is positive recurrent

De Veciana, Lee & Konstantopoulos 1999; Bonald & Massoulié 2001

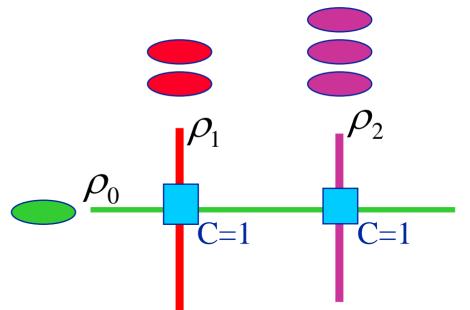
What goes wrong without fairness?

Suppose vertical streams have priority: then condition for stability is

$$\rho_0 < (1 - \rho_1) (1 - \rho_2)$$

and not

$$\rho_0 < \min\{1 - \rho_1, 1 - \rho_2\}$$



Bonald & Massoulié 2001

Heavy traffic

We're interested in what happens when we approach the edge of the achievable region, when

$$\sum_{r} A_{jr} \rho_{r} \approx C_{j} \quad j \in J$$

Fluid model for a network operating under a fair bandwidth-sharing policy. K & Williams *Ann Appl Prob 2004* Product form stationary distributions for diffusion approximations to a flow level model operating under a proportional fair sharing policy. Kang, K, Lee & Williams *Performance Evaluation Review 2007* State space collapse and diffusion approximation for a network operating under a proportional fair sharing policy. Kang, K, Lee & Williams

Fluid and diffusion scalings

Consider a sequence of networks, labelled by N, where as $N \rightarrow \infty$,

$$v^N \to v, \quad \mu^N \to \mu, \quad N(A\rho^N - C) \to \theta$$

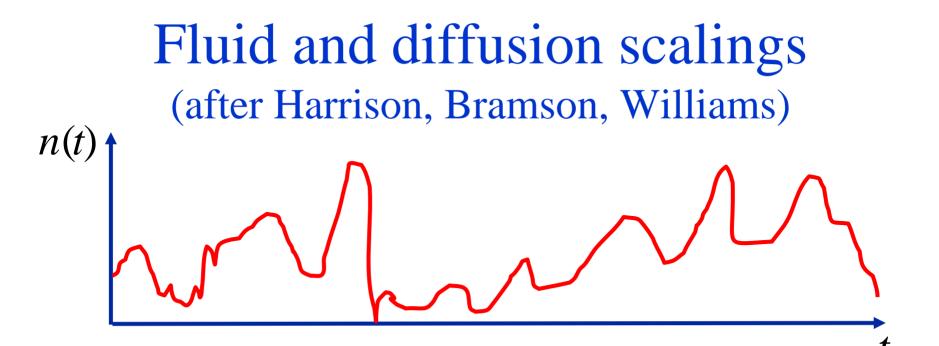
(and thus $A\rho = C$)

Fluid scaling:

 $n^{N}(Nt)$

Diffusion scaling:

$$\frac{n^{N}(N^{2}t)}{N}$$



Fluid scaling:

$$\frac{n^{N}(Nt)}{N}$$

On this time scale, traffic and capacity are balanced, and we expect a law of large numbers Diffusion scaling: $\underline{n^N(N^2t)}$

On this time scale, there is a drift of θ , and we expect a central limit theorem

Balanced fluid model

Suppose
$$\sum_{r} A_{jr} \rho_{r} = C_{j} \quad j \in J$$

and consider differential equations

$$\frac{\mathrm{d}n_r(t)}{\mathrm{d}t} = v_r - n_r x_r(n)\mu_r \qquad (n_r > 0) \qquad r \in R$$

First let's substitute for the values of $x_r(n)$, $r \in R$, to give:

$$\frac{\mathrm{d}n_r(t)}{\mathrm{d}t} = v_r - n_r \mu_r \left(\frac{w_r}{\sum_j A_{jr} p_j(n)}\right)^{1/\alpha} \quad r \in \mathbb{R}$$

(care needed when
$$n_r = 0$$
).

Thus, at an invariant state,

$$n_r = \frac{v_r}{\mu_r} \left(\frac{\sum_j A_{jr} p_j(n)}{w_r} \right)^{1/\alpha} \quad r \in \mathbb{R}$$

State space collapse: invariant manifold

The following are equivalent:

- *n* is an invariant state
- there exists a non-negative vector pwith $\sqrt{\sum_{i=1}^{1/\alpha}}$

$$n_r = \frac{v_r}{\mu_r} \left(\frac{\sum_j A_{jr} p_j}{w_r} \right)^{1/\alpha} \quad r \in \mathbb{R}$$

Thus the set of invariant states forms a J dimensional manifold, parameterized by p.

A potential function

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Let
$$F(n) = \frac{1}{\alpha + 1} \sum_{r} v_r w_r \mu_r^{\alpha - 1} \left(\frac{n_r}{v_r}\right)^{\alpha + 1}$$

(following Bonald and Massoulié 2001). Then

$$\frac{\mathrm{d}}{\mathrm{d}t}F(n(t)) \le 0$$

with equality only if n is an invariant state.

Workloads

Let
$$W_j(n(t)) = \sum_r A_{jr} \frac{n_r(t)}{\mu_r}$$

the workload for resource j. Then

$$\frac{\mathrm{d}}{\mathrm{d}t}W_j(n(t)) \ge 0, \quad p_j(n(t))\frac{\mathrm{d}}{\mathrm{d}t}W_j(n(t)) = 0$$

Extremal characterization of an invariant state

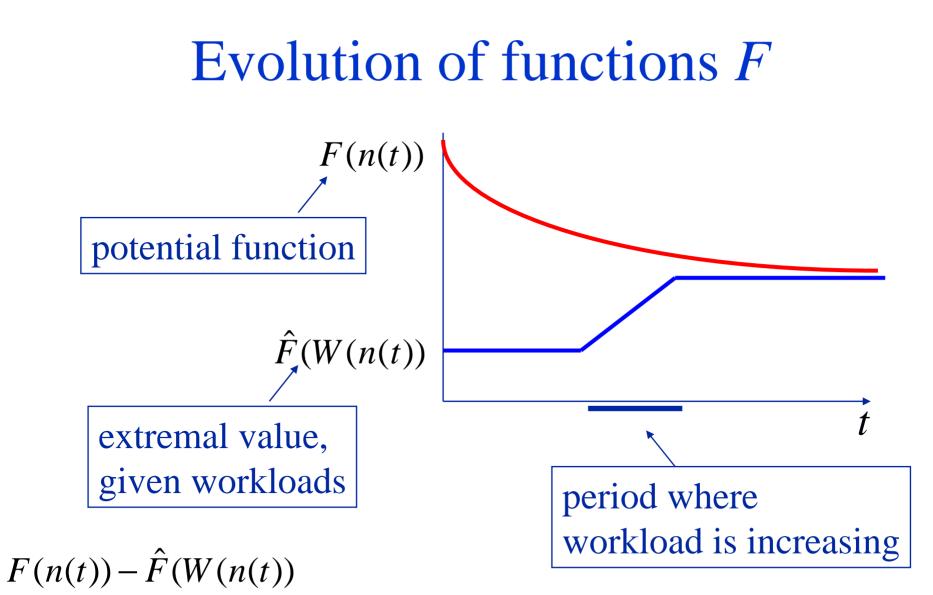
Minimize
$$F(n) = \frac{1}{\alpha + 1} \sum_{r} v_r w_r \mu_r^{\alpha - 1} \left(\frac{n_r}{v_r}\right)^{\alpha + 1}$$

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subject to
$$\sum_{r} A_{jr} \frac{n_{r}}{\mu_{r}} \ge W_{j} \quad j \in J, \quad n_{r} \ge 0 \quad r \in R$$

Solution is $n_{r} = \frac{V_{r}}{\mu_{r}} \left(\frac{\sum_{j} A_{jr} \hat{p}_{j}(W)}{w_{r}} \right)^{1/\alpha} \quad r \in R$

 $\hat{p}_i(W)$ - Lagrange multiplier for the resource *j* workload constraint



provides a Lyapunov function which shows convergence to the invariant manifold

The case $\alpha = 1$

$$n_r = \frac{\nu_r}{\mu_r w_r} \sum_j A_{jr} p_j \quad r \in R$$

Define diagonal matrices

$$\rho = diag(v_r / \mu_r, r \in R), w = diag(w_r, r \in R)$$

Then $n = \rho w^{-1} A^T p$ and so $W = (A \mu^{-1}) n = (A \mu^{-1} \rho w^{-1} A^T) p$, $p = (A \mu^{-1} \rho w^{-1} A^T)^{-1} W$

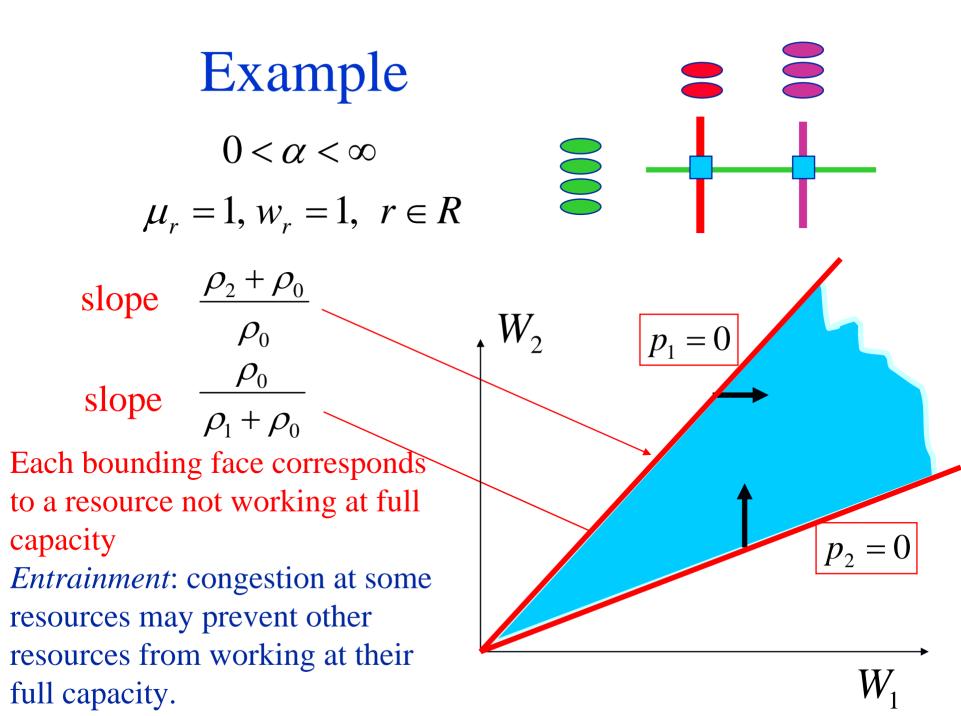
Thus W lies in the polyhedral cone {W: $W = A\mu^{-1}\rho w^{-1}A^T p, p \ge 0$ }

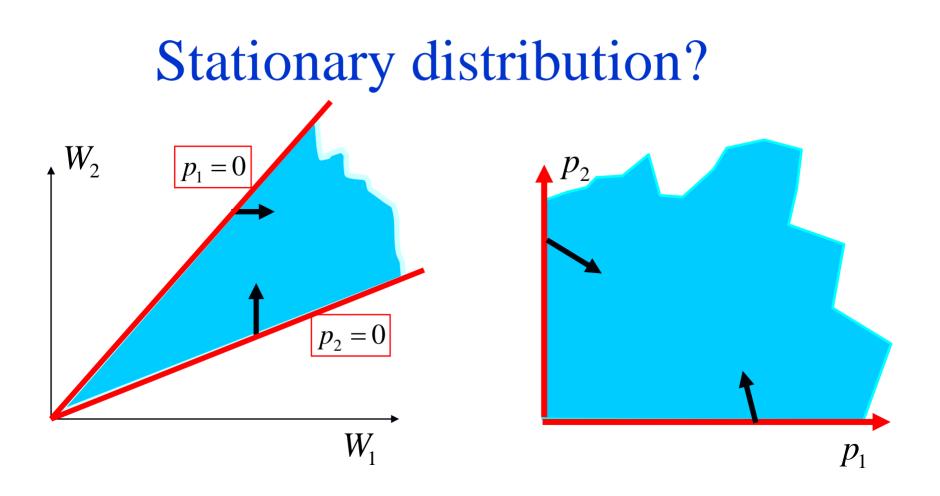
More generally, W lie in the cone

$$(A\mu^{-1}\rho w^{-1/\alpha})C_{\alpha}$$

where

$$C_{\alpha} = \{ (\sum_{r} A_{jr} p_{j})^{1/\alpha}, r \in R \}$$

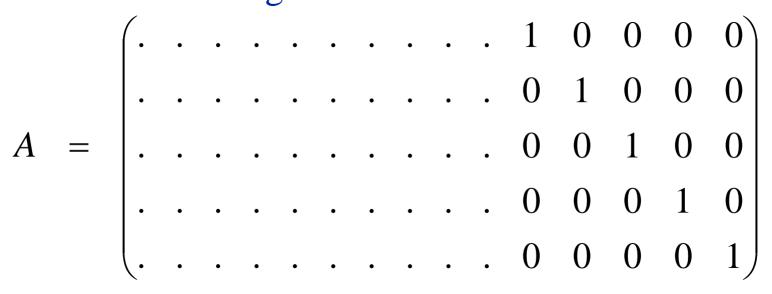




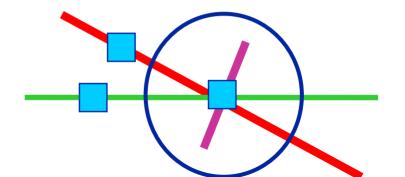
Williams (1987) determined sufficient conditions, in terms of the reflection angles and covariance matrix, for a SRBM in a polyhedral domain to have a product form invariant distribution – a skew symmetry condition

Local traffic condition

Assume the matrix A contains the columns of the unit matrix amongst its columns:



i.e. each resource has some local traffic -



Product form under proportional fairness $\alpha = 1, w_r = 1, r \in R$

Under the stationary distribution for the reflected Brownian motion, the (scaled) components of pare independent and exponentially distributed. The corresponding approximation for n is

$$n_r \approx \rho_r \sum_j A_{jr} p_j \quad r \in R$$

where

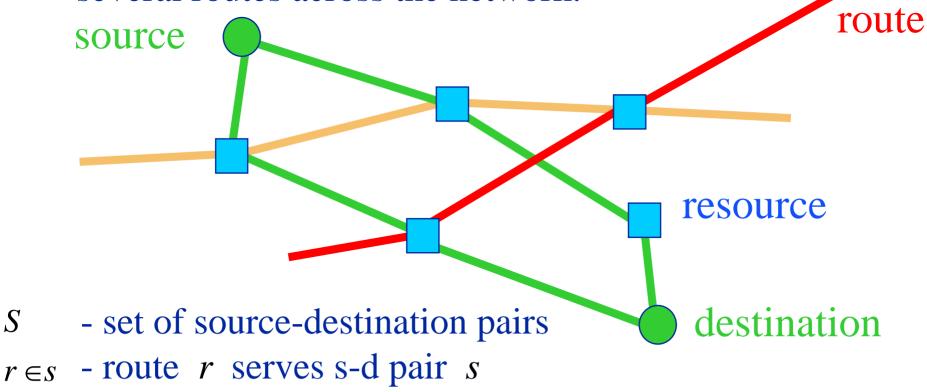
$$p_j \sim \operatorname{Exp}(C_j - \sum_r A_{jr}\rho_r) \quad j \in J$$

Dual random variables are independent and exponential

Multipath routing

Suppose a source-destination pair has access to several routes across the network:

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Combined multipath routing and congestion control: a robust Internet architecture. Key, Massoulié & Towsley

Routing and optimization formulation

Suppose x = x(n) is chosen to

maximize

$$\sum_{s} n_s \log(x_s)$$

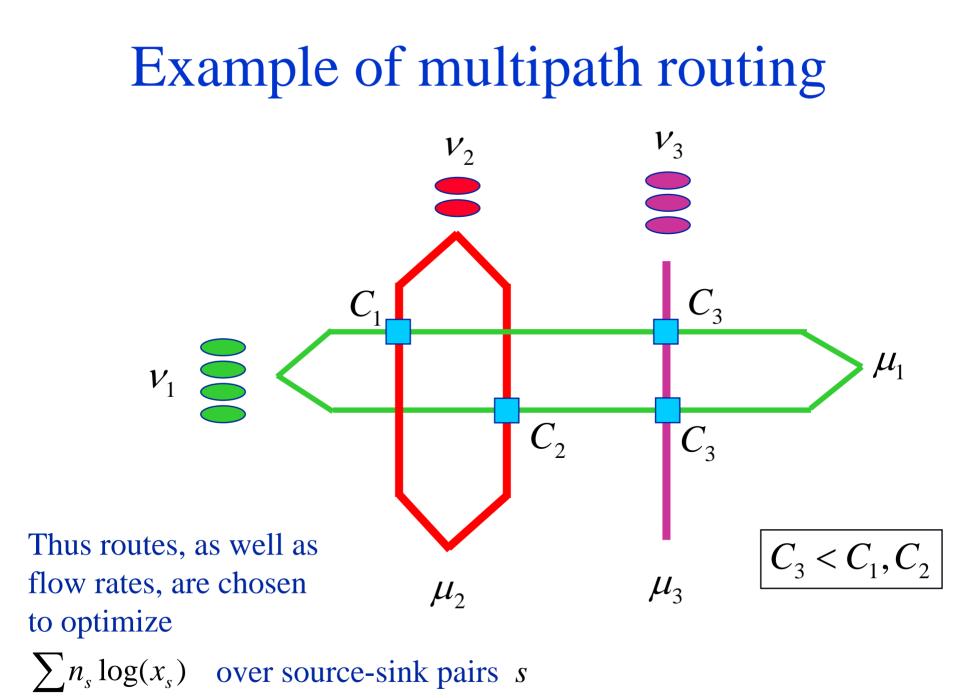
subject to

$$\sum_{r} H_{sr} y_{r} = x_{s} \quad s \in S$$

$$\sum_{r} A_{jr} n_{r} y_{r} \leq C_{j} \quad j \in J$$

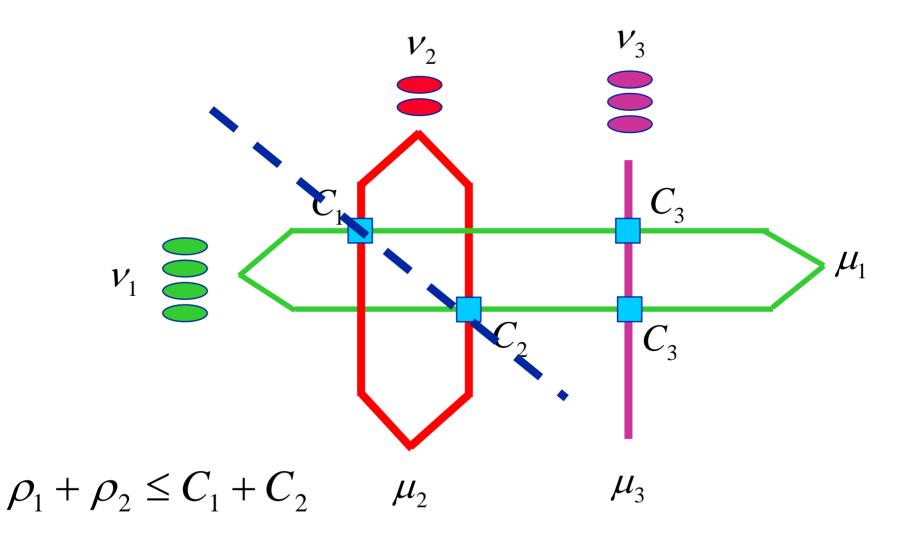
$$y_{r} \geq 0 \quad r \in R$$

(*H* is an incidence matrix, showing which routes serve a source-destination pair)

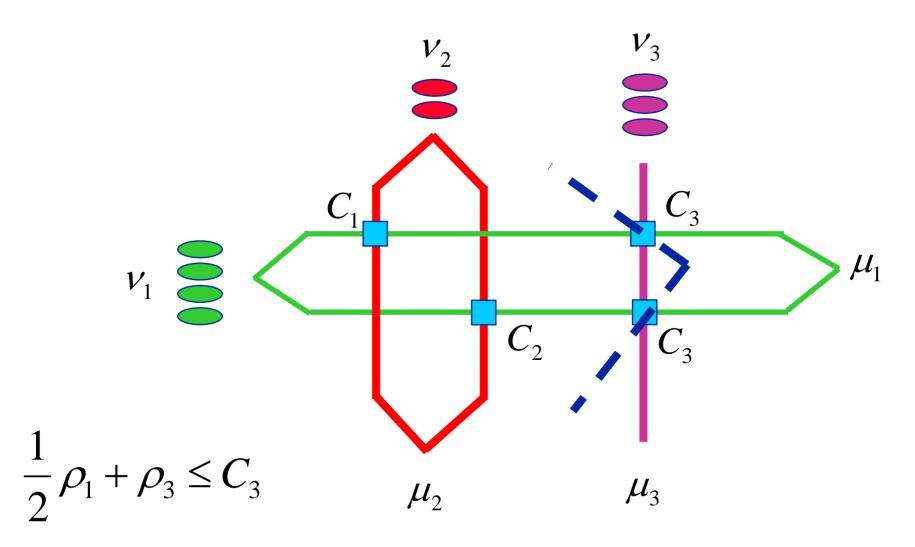


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First cut constraint



Second cut constraint



Generalized cut constraints

In general, stability requires

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$$\sum \overline{A}_{js} \rho_s < \overline{C}_j \quad j \in \overline{J}$$

- a collection of generalized cut constraints. Provided A contains a unit matrix, we again have the approximation

where

p

$$n_{s} \approx \rho_{s} \sum_{j \in \overline{J}} A_{js} p_{j} \quad s \in S$$
$$_{j} \sim \operatorname{Exp}(\overline{C}_{j} - \sum_{s} \overline{A}_{js} \rho_{s}) \quad j \in \overline{J}$$

Again independent dual random variables, now one for each generalized cut constraint

Models of routing and congestion control

- Flow level Markov chain model
- Heavy traffic and proportional fairness give product form for dual variables
- A dual variable for each generalized cut constraint, under multipath routing
- Good behaviour, achieved without prior knowledge of which cut constraints bite