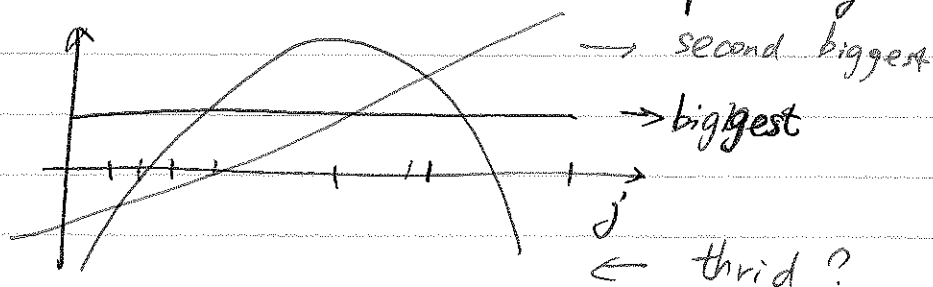


$$y_t^j \equiv -\frac{1}{T_j} \log B(t, t+T_j)$$

$j=1, 2, \dots, J$. Now we consider y_t as a J -vector, and we can do some basic statistics, like ~~ea~~ calculate the sample means $\bar{y}_t = \frac{1}{t} \sum_{i=1}^t y_i$ and sample covariance

$$V_t = \frac{1}{t} \sum_{i=1}^t (y_i - \bar{y}_t)(y_i - \bar{y}_t)^T$$

and then look at the eigenvalue structure of V_t . Typically, we find that there are 2-3 eigenvalues that "matter" with corresponding e-vectors



A 1-factor model could not generate such dynamics...

Nov 24 Thursday

AFM

HJM

$$\begin{aligned} E_t \exp(-\int_0^T r_s ds) &= \exp[-\int_0^t r_s ds - \int_t^T f_{ts} ds] \\ &= \exp(-\int_0^t f_{0s} ds) \\ &\quad \cdot \exp(-\int_0^t \Sigma_{sT} dB_s - \frac{1}{2} \int_0^t \Sigma_{sT}^2 ds) \end{aligned}$$

$$df_{ts} = \sigma_{ts} dB_t + \alpha_{ts} dt$$

Taking logs, we get

$$\begin{aligned} &\int_0^T f_{0s} ds + \int_0^t \Sigma_{sT} dB_s + \int_0^t \frac{1}{2} \Sigma_{sT}^2 ds \\ &= \int_0^t r_s ds + \int_t^T \{ f_{0s} + \int_0^t \sigma_{us} dB_u + \int_0^t \alpha_{us} du \} ds \\ &= \int_0^t r_s ds + \int_t^T f_{0s} ds + \int_0^t (\int_t^T \sigma_{us} ds) dB_u \\ &\quad + \int_0^t (\int_t^T \alpha_{us} ds) du. \end{aligned}$$

Hence

$$\begin{aligned} &\int_0^t f_{0s} ds - \int_0^t r_s ds + \int_0^t \Sigma_{sT} dB_s + \int_0^t \frac{1}{2} \Sigma_{sT}^2 ds \\ &= \int_0^t (\int_t^T \sigma_{us} ds) dB_u + \int_0^t (\int_t^T \alpha_{us} ds) du, \\ &= \int_0^t (\int_t^T \sigma_{us} ds) dB_u + \int_0^t (\int_0^T \alpha_{us} ds - \int_0^t \alpha_{us} ds) du \end{aligned}$$

Now

$$\begin{aligned} \int_0^t (f_{0s} - r_s) ds &= \int_0^t (f_{0s} - f_{ss}) ds = - \int_0^t \{ \int_0^s \sigma_{us} dB_u + \int_0^s \alpha_{us} du \} ds \\ &= - \int_0^t (\int_u^t \sigma_{us} ds) dB_u - \int_0^t (\int_u^t \alpha_{us} ds) du \end{aligned}$$

Looking at the integrals dB_s , we conclude that

$$\Sigma_{uT} = \int_0^T \sigma_{us} ds$$

The remaining terms give us