

## Analysis of Survival Data

# Competing Risks (2014)

## 1 Introduction

### 1.1 Context

A *competing risks* analysis is a time-to-event analysis where (1) individuals are at risk of more than one different event and (2) after the first event the individual is not at risk of a second event.

A medical example would be a clinical trial where individuals are at risk of dying from several causes.

### 1.2 Statistical Model

Each individual is at risk of two events of interest ( $A$  and  $B$ ) and of censoring  $C$ . The restriction to *two* events of interest is merely to simplify the notation, there is no difficulty about extending the analysis to more than two events.

We imagine that there are two times-to-event –  $T_A, T_B$  – which are independent given a set of modelled baseline covariates  $Z$ . We will use  $J$  as a shorthand for the composite event ‘ $A$  or  $B$ ’ so that  $T_J = T_{A \cup B} = \min(T_A, T_B)$ . We assume  $T_A \neq T_B$ : which means there is a well defined ‘first’ event  $E \in \{A, B\}$  such that  $E = A$  iff  $T_J = T_A$ .

The results will be presented generally in terms of event  $A$ , similar results hold for event  $B$  by symmetry.

## 2 Lecture

### 2.1 Cause-Specific Hazard

The *cause-specific hazard*  $h_A(t)$  for event  $A$  is the event rate at time  $t$  for  $A$  given no event of any sort ( $A$  or  $B$ ) before time  $t$ :

$$\begin{aligned} h_A(t) &= \lim_{\Delta \downarrow 0} \left\{ \frac{1}{\Delta} \mathbb{P}[t < T_A \leq t + \Delta | t < T_J] \right\} \\ &= \lim_{\Delta \downarrow 0} \left\{ \frac{1}{\Delta} \mathbb{P}[t < T_A \leq t + \Delta | t < T_A] \right\} \end{aligned}$$

where the second equality is a consequence of  $A$  and  $B$  being independent.

### 2.2 Competing risks

The hazard  $h_J(t)$  for the event death-from-any-cause ( $A \cup B$ ) is given by the sum of hazards for the individual events:

$$h_J(t) = h_A(t) + h_B(t)$$

where  $h_A(t)$  is defined as:

$$h_A(t) = \lim_{\Delta \downarrow 0} \left\{ \frac{1}{\Delta} \mathbb{P} [t < T_A \leq t + \Delta | t < T_J] \right\},$$

and the same relationship holds for the integrated hazards:

$$H_J(t) = H_A(t) + H_B(t).$$

The probability of no event of either sort in  $[0, t]$  is given by:

$$\mathbb{P} [t < T_J] = F_J(t) = \exp \{-H_J(t)\}.$$

### 2.3 Cause Specific Density

The density  $f_A(t)$  of event  $A$  in the absence of event  $B$  is not the same as the density  $\tilde{f}_A(t)$  in the presence of competing event  $B$  because if  $T_B < T_A$  there is no contribution to the density of  $A$ . The density  $\tilde{f}_A(t)$  is the *cause specific density* and is defined as:

$$\tilde{f}_A(t) = \lim_{\Delta \downarrow 0} \left\{ \frac{1}{\Delta} \mathbb{P} [(t < T_J \leq t + \Delta) \& (T_J = T_A)] \right\}.$$

The (ordinary) density can be written:

$$f_A(t) = h_A(t)F_A(t)$$

and by analogy the cause specific density is given by:

$$\tilde{f}_A(t) = h_A(t)F_J(t)$$

where the substitution of  $F_J$  for  $F_A$  accounts for  $B$  occurring before  $A$ .

### 2.4 Cumulative Risk Function

The probability of an event occurring in  $[0, t]$  and that event being  $A$  is known as the *cumulative risk function* for  $A$ , which will be denoted as  $G_A(t)$ . The cumulative risk function is obtained by integrating the cause-specific density:

$$\begin{aligned} G_A(t) &= \int_0^t \tilde{f}_A(t') dt' = \int_0^t h_A(t') F_J(t') dt' \\ &= \int_0^t h_A(t') \exp \left\{ - \int_0^{t'} h_A(t'') dt'' - \int_0^{t'} h_B(t'') dt'' \right\} dt'. \end{aligned} \quad (1)$$

Note that if  $F_J(\infty) = 0$  then  $G_A(\infty) + G_B(\infty) = 1$ .

### 2.5 Non-parametric Estimation of the Cumulative Risk Function

We assume no ties in the dataset (though the methods can be easily extended to account for them).

There are  $d$  event times  $a_1 \dots a_d$ , with  $a_j < a_{j+1}$ , and exactly one event,  $A$  or  $B$ , occurs at each event time. The marker  $\varepsilon_j$  indicates which event occurred at  $a_j$  ( $\varepsilon_j \in \{A, B\}$ ) and there are  $r_j$  individuals in the risk set at that time. For notational convenience,  $a_0 = 0$  by definition.

The Nelson-Aalen and Kaplan-Meier estimators for the joint event  $J = A \cup B$  have the standard forms. The Nelson-Aalen estimate for the joint integrated hazard is given by:

$$\begin{aligned}\hat{H}_J(t) &= \sum_{j:a_j \leq t} \frac{1}{r_j} \\ &= \sum_{j:a_j \leq t} \hat{h}_{J,j}\end{aligned}$$

where  $\hat{h}_{J,j} = 1/r_j$ . The Kaplan-Meier estimate for the joint survivor function is given in the same notation by:

$$\hat{\mathbb{P}}[t < T_J] = \hat{F}_J(t) = \prod_{j:a_j \leq t} (1 - \hat{h}_{J,j}) \quad (2)$$

and note that this is ultimately based on  $\hat{\mathbb{P}}[a_{j-1} < T_J \leq a_j | a_{j-1} < T_J] = \hat{h}_{J,j}$ .

The estimate of the cause specific integrated hazard for  $A$  is simply the Nelson-Aalen estimator counting only events  $A$ :

$$\hat{H}_A(t) = \sum_{j:a_j \leq t} \frac{\mathbb{I}[\varepsilon_j = A]}{r_j} = \sum_{j:a_j \leq t} \hat{h}_{A,j}$$

with

$$\hat{h}_{A,j} = \mathbb{I}[\varepsilon_j = A] / r_j = \hat{\mathbb{P}}[(a_{j-1} < T_J \leq a_j) \& (T_J = T_A) | a_{j-1} < T_J]. \quad (3)$$

Note that  $\hat{H}_A(t) + \hat{H}_B(t) = \hat{H}_J(t)$ .

An estimate for the cause specific risk function for event  $A$  is obtained by breaking down the risk function into the individual time intervals and summing the probability of event  $A$  occurring in that interval:

$$\hat{G}_A(t) = \sum_{j:a_j \leq t} \hat{\mathbb{P}}[(a_{j-1} < T_J \leq a_j) \& (T_J = T_A)].$$

Each unconditional probability is the product of the probability that there is no event in  $[0, a_{j-1}]$  multiplied by the probability of event  $A$  in  $]a_{j-1}, a_j]$  conditional on no events in  $[0, a_{j-1}]$ :

$$\hat{G}_A(t) = \sum_{j:a_j \leq t} \hat{\mathbb{P}}[(a_{j-1} < T_J \leq a_j) \& (T_J = T_A) | a_{j-1} < T_J] \hat{\mathbb{P}}[a_{j-1} < T_J]. \quad (4)$$

Note that we have just written down the non-parametric estimation equivalents of (1). The left hand factor of each term in (4) has been derived already (3) as  $\hat{h}_{A,j}$  and the right hand factor is the Kaplan-Meier estimator (2) of  $F_J(t)$

evaluated at  $a_j$ :

$$\begin{aligned}\hat{G}_A(t) &= \sum_{j:a_j \leq t} \hat{h}_{A,j} \prod_{j'=1}^{j-1} \left(1 - \hat{h}_{J,j'}\right). \\ &= \sum_{j:a_j \leq t} \frac{\mathbb{I}[\varepsilon_j = A]}{r_j} \prod_{j'=1}^{j-1} \left(1 - \frac{1}{r_{j'}}\right)\end{aligned}\tag{5}$$

Expression (5) is known as the Aalen-Johansen estimate of the cumulative risk function.

**Exercise** Verify that  $\hat{G}_A(t) + \hat{G}_B(t) + \hat{F}_J(t) = 1$ .